

問題解答

2. 力の釣合い

[問題 2.2]

$$(1) \quad \sum V = 0: N_{AC} \sin \theta - 2 = 0, \therefore N_{AC} = 3.333 \text{ N}, \quad \sum H = 0: -3.333 \cos \theta - N_{BC} = 0, \therefore N_{BC} = -2.667 \text{ N}$$

$$(2) \quad \sum V = 0: -N_{AC} \sin 30^\circ - N_{BC} \sin 60^\circ - 2 = 0, \quad \sum H = 0: N_{AC} \cos 30^\circ + N_{BC} \cos 60^\circ = 0,$$

上第 2 式より $N_{AC} = -N_{BC} \frac{\cos 60^\circ}{\cos 30^\circ}$, これと第 1 式より $N_{AC} = 2.0 \text{ N}$, $N_{BC} = -3.464 \text{ N}$

$$(3) \quad \sum V = 0: N_{AC} \sin 60^\circ + N_{BC} \sin 30^\circ - 3 = 0, \quad \sum H = 0: -N_{AC} \cos 60^\circ + N_{BC} \cos 30^\circ = 0,$$

上第 2 式より $N_{AC} = N_{BC} \frac{\cos 30^\circ}{\cos 60^\circ}$, これと第 1 式より $N_{AC} = 2.598 \text{ N}$, $N_{BC} = 1.5 \text{ N}$

[問題 2.3]

$$(1) \quad \sum M_B = 0: 5R_A - 10 \cdot 2 = 0, \therefore R_A = 4.0 \text{ N}, \quad \sum V = 0: R_A - 10 + R_B = 0, \therefore R_B = 6.0 \text{ N}$$

$$(2) \quad \sum M_B = 0: -5 \cdot 9 + 6R_A - 3 \cdot 3 = 0, \therefore R_A = 9.0 \text{ N},$$

$$\sum V = 0: -5 + R_A - 3 + R_B = 0, \therefore R_B = -1.0 \text{ N}$$

$$(3) \quad \sum M_B = 0: 5R_A - 12 \sin 60^\circ \cdot 4 - 10 \cdot 2 = 0, \therefore R_A = 12 \cdot 314 \text{ N}$$

$$\sum V = 0: R_A - 12 \sin 60^\circ - 10 + R_B = 0, \therefore R_B = 8.07 \text{ N},$$

$$\sum H = 0: H_A = -12 \cos 60^\circ = 0, \therefore H_A = 6.0 \text{ N}$$

$$(4) \quad \sum M_A = 0: 3 \cdot 2 + 5 - R_B \cdot 8 = 0, \therefore R_B = 11/8 = 1.375 \text{ N}$$

$$\sum M_b = 0: -R_A \cdot 8 - 3 \cdot 6 + 5 = 0, \therefore R_A = -13/8 = -1.625 \text{ N}$$

3. 力の合成・分解

[問題 3.1]

$$(1) \quad R = 5 - 3 + 4 = 6 \text{ kN} \quad (\text{右向き})$$

$$(2) \quad R = \sqrt{(4 + 3 \cos 60^\circ)^2 + (3 \sin 60^\circ)^2} = \sqrt{37} = 6.083 \text{ kN}$$

$$\theta = \tan^{-1} \left(\frac{3 \sin 60^\circ}{4 + 3 \cos 60^\circ} \right) = \tan^{-1} \left(\frac{3\sqrt{3}}{11} \right) = 25^\circ 17' 05'' \quad (P_2 \text{ から左回りに } 25^\circ 17' 05'' \text{ の方向})$$

$$(3) \quad R = \sqrt{(4 + 3 \cos 120^\circ)^2 + (3 \sin 120^\circ)^2} = \sqrt{13} = 3.606 \text{ kN}$$

$$\theta = \tan^{-1} \left(\frac{3 \sin 120^\circ}{4 + 3 \cos 120^\circ} \right) = \tan^{-1} \left(\frac{3\sqrt{3}}{5} \right) = 46^\circ 06' 07'' \quad (P_2 \text{ から左回りに } 46^\circ 06' 07'' \text{ の方向})$$

$$(4) \quad R = 6.59 \text{ kN}, \quad \tan \alpha = 0.754$$

[問題 3.2]

$$(4) \quad R = \sqrt{(4 \cos 60^\circ + 3 \cos 45^\circ - 3 \cos 30^\circ)^2 + (4 \sin 60^\circ + 3 \sin 30^\circ - 3 \sin 45^\circ)^2} = 3.225 \text{ kN}$$

$$\theta = \tan^{-1} \left(\frac{4 \sin 60^\circ + 3 \sin 30^\circ - 3 \sin 45^\circ}{4 \cos 60^\circ + 3 \cos 45^\circ - 3 \cos 30^\circ} \right) = 61^\circ 48' 58'' \quad (x \text{ 軸から } 61^\circ 48' 58'' \text{ の方向})$$

$$(5) \quad R = \sqrt{(3 \cos 30^\circ - 4 \cos 45^\circ - 3 \cos 60^\circ + 2 \cos 30^\circ)^2 + (3 \sin 30^\circ + 4 \sin 45^\circ - 3 \sin 60^\circ - 2 \sin 30^\circ)^2}$$

$$= 0.733 \text{ kN}$$

$$\theta = \tan^{-1} \left(\frac{3 \sin 30^\circ + 4 \sin 45^\circ - 3 \sin 60^\circ - 2 \sin 30^\circ}{3 \cos 30^\circ - 4 \cos 45^\circ - 3 \cos 60^\circ + 2 \cos 30^\circ} \right) = 89^\circ 51' 59'' \quad (x \text{ 軸から } 89^\circ 51' 59'' \text{ の方向})$$

[問題 3.3] (省略)

[問題 3.4]

(1) $P_x = 5 \cos 30^\circ = 4.33 \text{kN}$ (左向き), $P_y = 5 \sin 30^\circ = 2.50 \text{kN}$ (下向き)

(2)
$$\left. \begin{aligned} P_x + P_y \cos 60^\circ &= 5 \cos 30^\circ \\ P_y \sin 60^\circ &= 5 \sin 30^\circ \end{aligned} \right\} \text{これより } P_x = 2.887 \text{kN}, \quad P_y = 2.887 \text{kN}$$

(3)
$$\left. \begin{aligned} P_x - P_y \cos 60^\circ &= 4 \cos 45^\circ \\ P_y \sin 60^\circ &= 4 \sin 45^\circ \end{aligned} \right\} \text{これより } P_x = 4.461 \text{kN}, \quad P_y = 3.266 \text{kN}$$

4. モーメント

[問題 4.1]

(1) $M_O = 2 \cdot 3 = 6 \text{Nm}$

(2) $M_O = -2 \cdot 3 = -6 \text{Nm}$

(3) $M_O = 3 \cdot 3 - 2 \cdot 4 + 4 \cdot 2 = 9 \text{Nm}$

(4) $M_O = 2 \cdot 5 - 3 \cdot 3 = 1 \text{Nm}$

(5) $M_O = -8 \sin 60^\circ \cdot 3 - 8 \cos 60^\circ \cdot 4 + 5 \sin 45^\circ \cdot 0 - 5 \cos 45^\circ \cdot 3 = -47.391 \text{Nm}$

[問題 4.2]

(1) $R = 3 + 5 = 8 \text{kN}$ (下向き), $x = \frac{5 \cdot 8}{8} = 5 \text{m}$ (点 O から右へ 5m の位置)

(1) $R = 3 - 4 + 3 + 3 = 5 \text{kN}$ (下向き), $x = \frac{-4 \cdot 3 + 3 \cdot 6 + 3 \cdot 10}{5} = 7.2 \text{m}$ (点 O から右へ 7.2m の位置)

(2) $R = 4 - 3 + 2 + 3 = 6 \text{kN}$ (下向き), $x = \frac{-4 \cdot 8 + 3 \cdot 5 - 2 \cdot 2 + 3 \cdot 2}{6} = -2.5 \text{m}$ (点 O から左へ 2.5m の位置)

(4) $R = \sqrt{3^2 + (-4 + 3 - 2 - 3)^2} = 3\sqrt{5} = 6.708 \text{kN}$

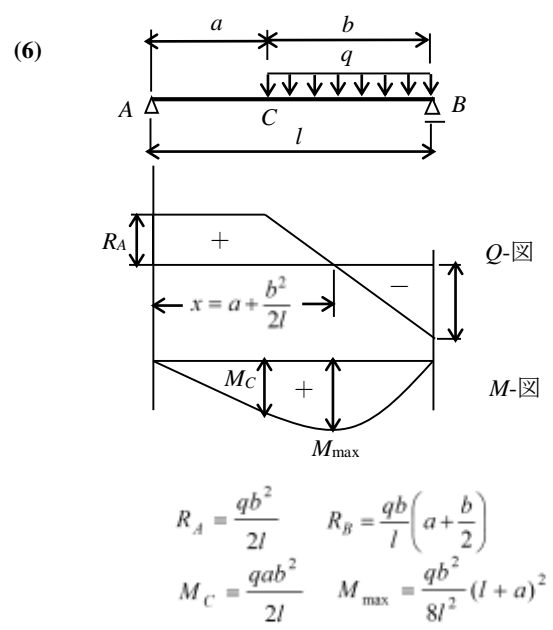
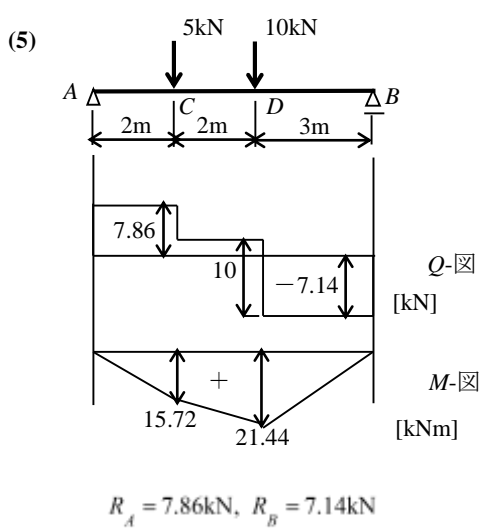
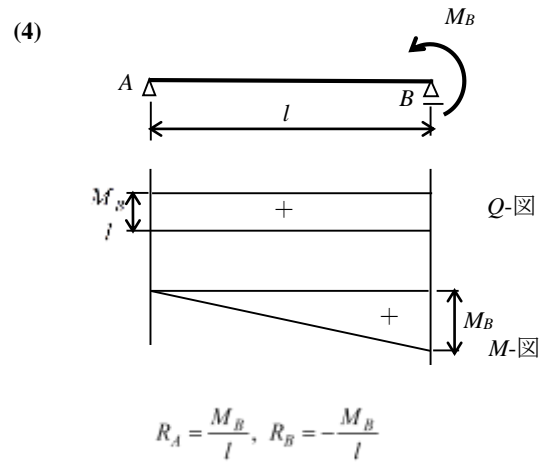
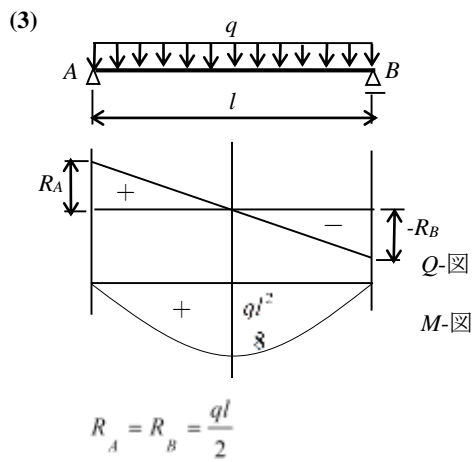
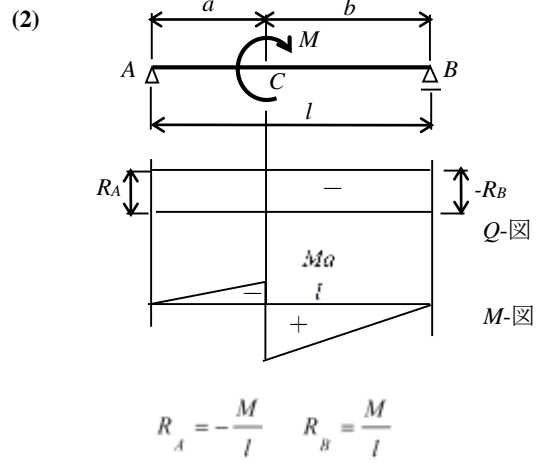
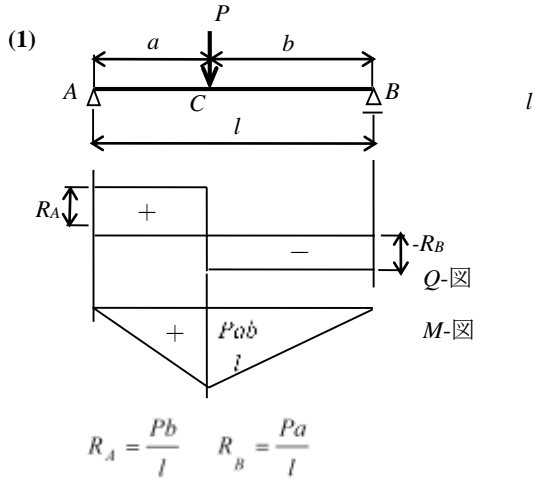
$$\tan \theta = \frac{-4 + 3 - 2 - 3}{-3} = 2, \quad \theta = \tan^{-1}(2) = 63^\circ 26' 05'' \text{ or } 243^\circ 26' 05''$$

合力 R は左斜め下がりであるから, 水平軸より $243^\circ 26' 05''$ の向き

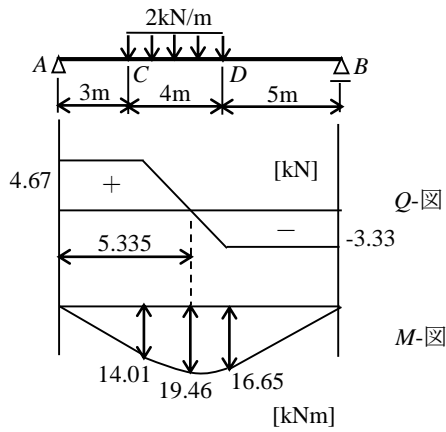
$$x = \frac{-3 \cdot 4 - 4 \cdot 8 + 3 \cdot 5 - 2 \cdot 2 + 3 \cdot 2}{6.708} = -4.025 \text{m}, \quad \text{点 O から合力までの垂直距離 } 4.025 \text{m}$$

5. 静定ばり

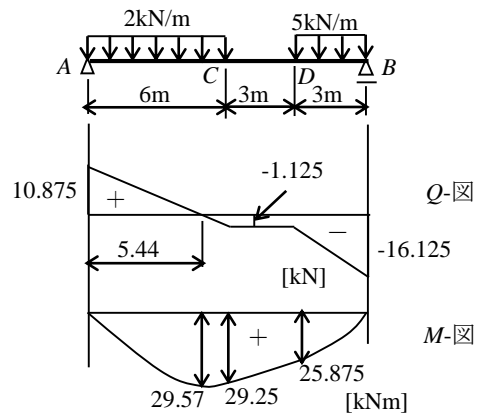
[問題 5.1]



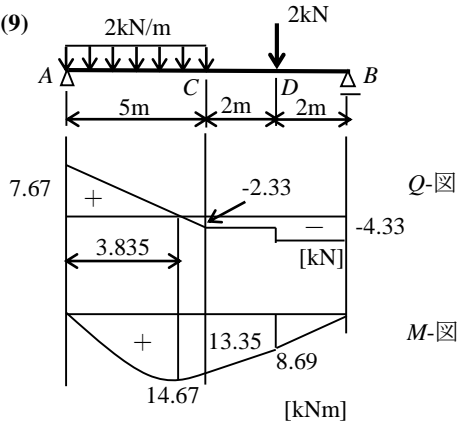
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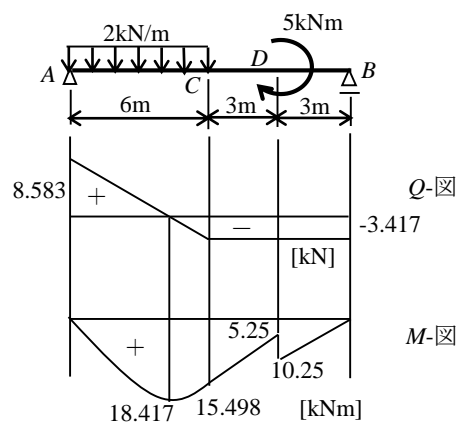
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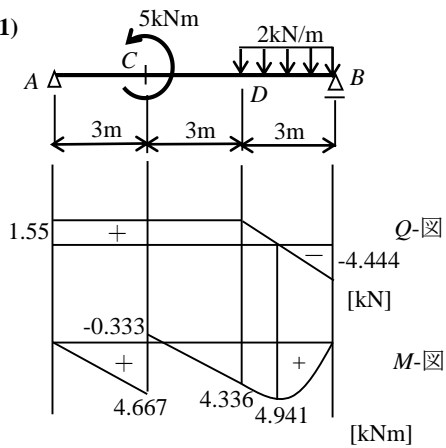
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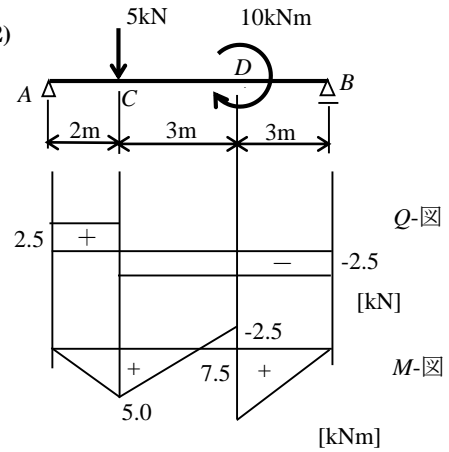
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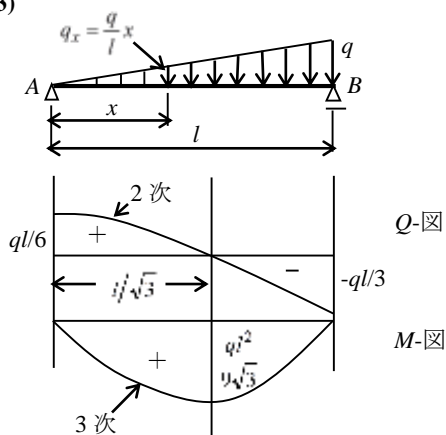
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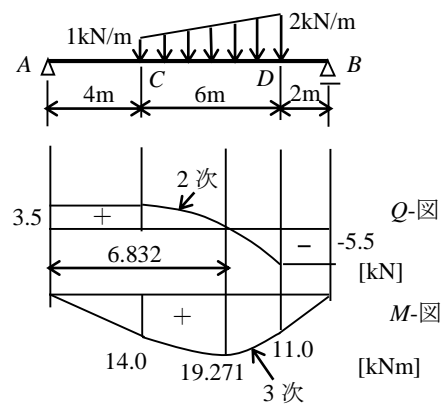
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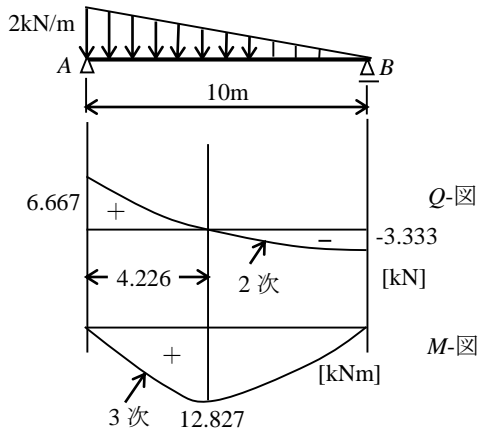
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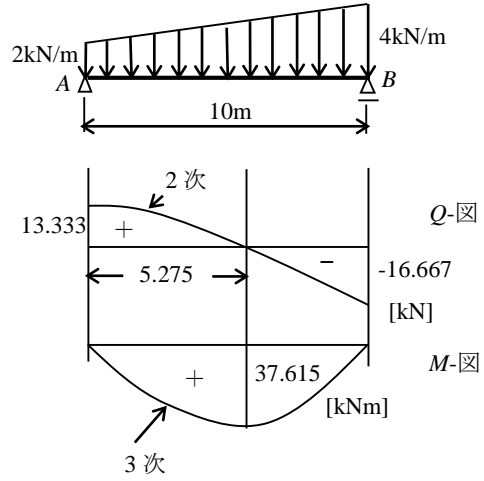
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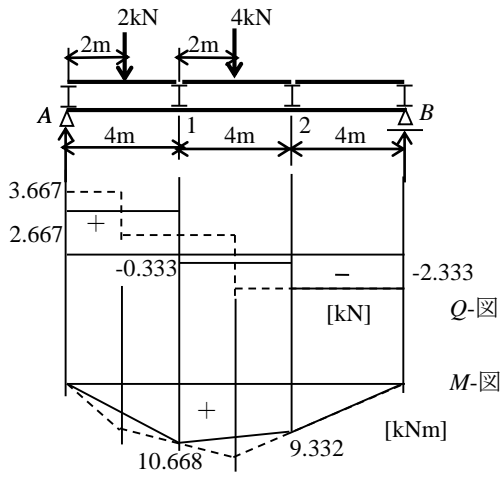


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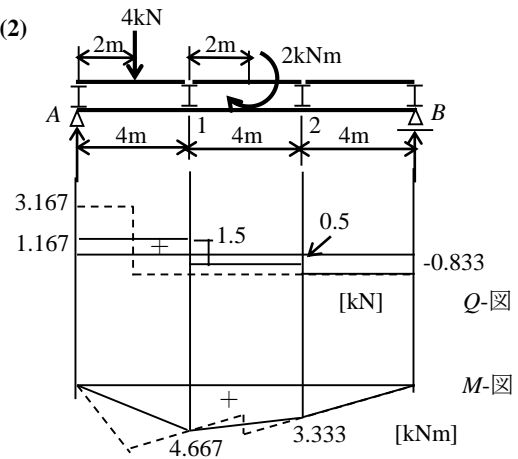


[問題 5.2]

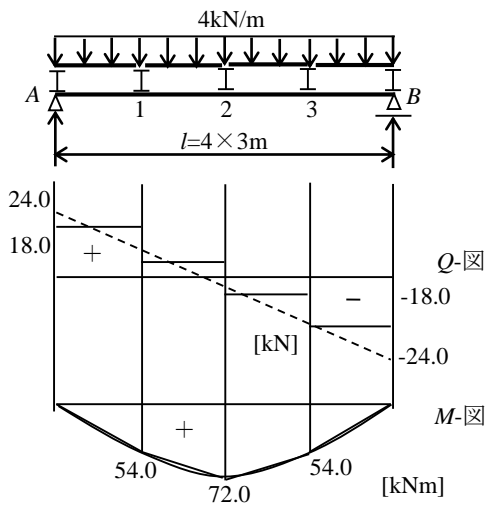
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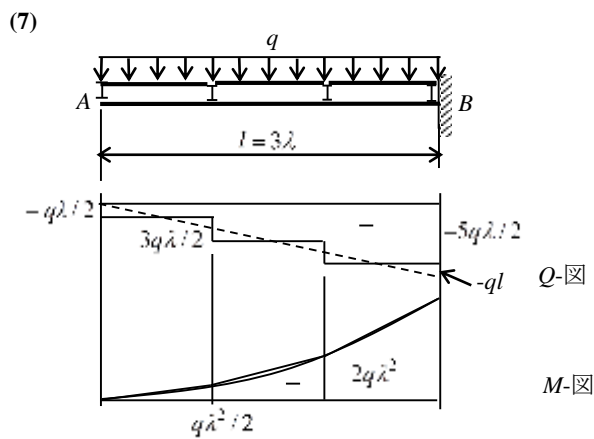
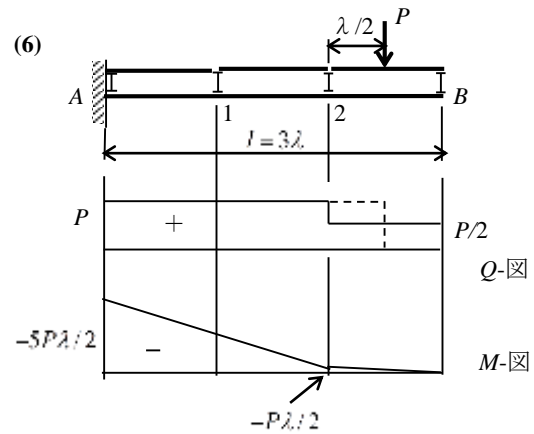
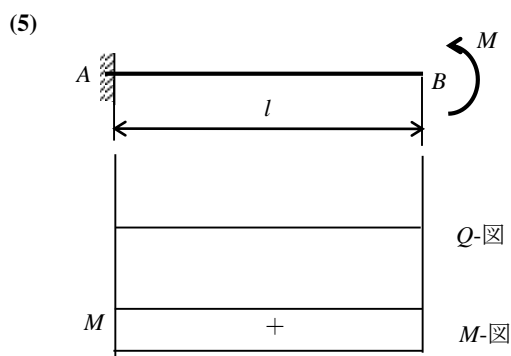
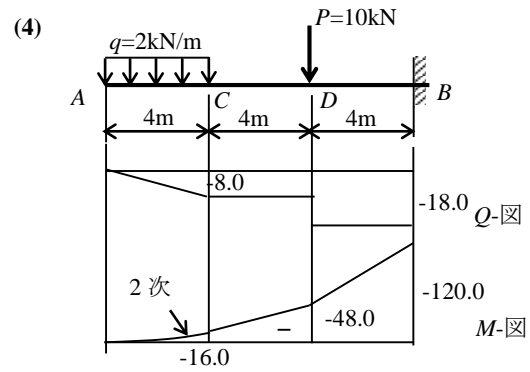
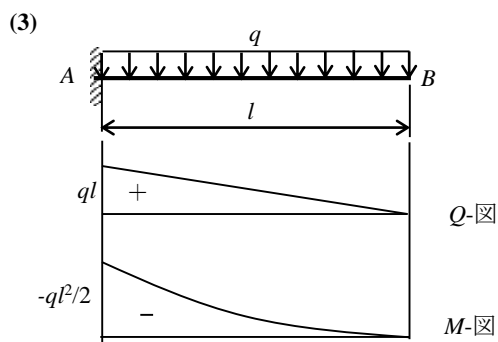
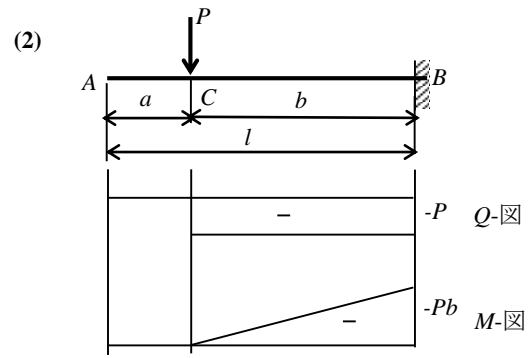
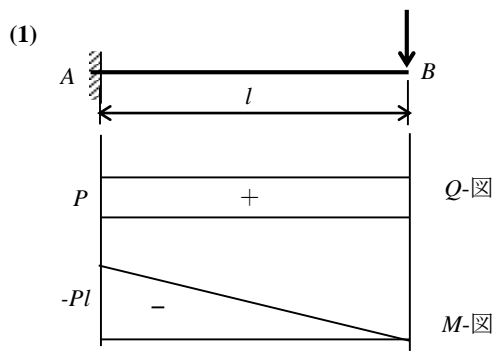
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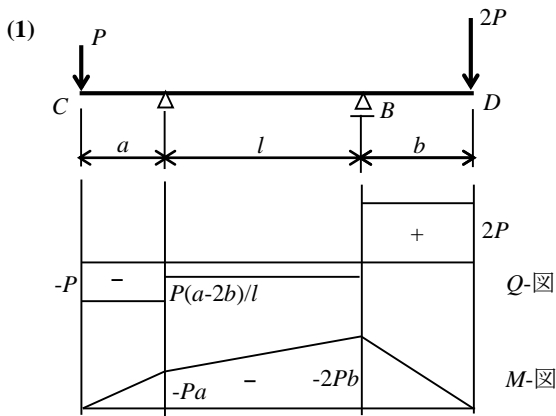
(3)



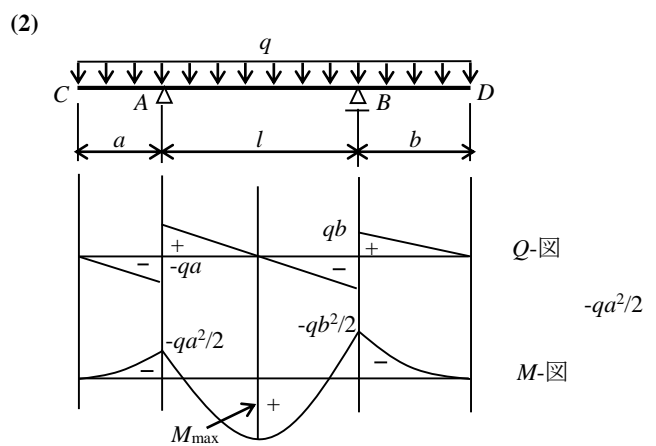
[問題 5.3]



[問題 5.4]

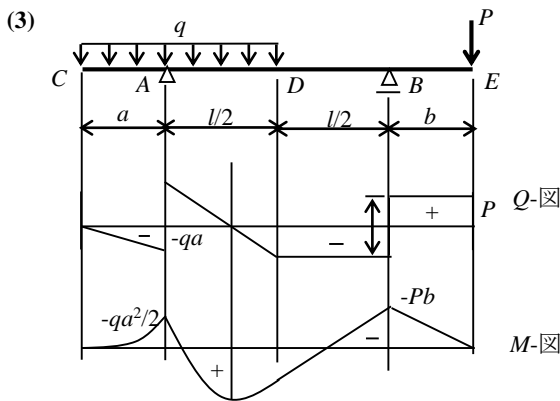


$$R_A = \frac{P}{l}(a+l-2b), \quad R_B = \frac{P}{l}(2l-a+2b)$$



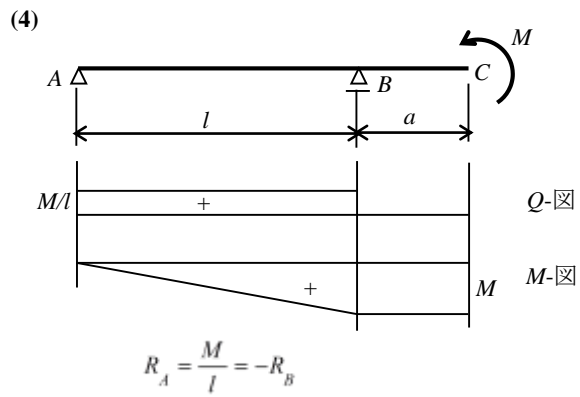
$$R_A = \frac{q}{2l} \{ (a+l)^2 - b^2 \}, \quad R_B = \frac{q}{2l} \{ (b+l)^2 - a^2 \}$$

$$x = \{ (a+l)^2 - b^2 \} / 2l, \quad M_{\max} = \frac{q}{8l^2} \{ (a+l)^2 - b^2 \} \{ (a-l)^2 - b^2 \}$$

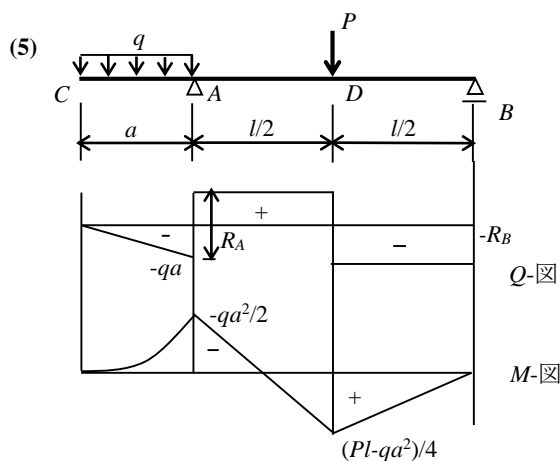


$$R_A = \frac{1}{l} [q(a+l/2)(a+3l/2)/2 - Pb]$$

$$R_B = \frac{1}{l} [q(a+l/2)(l/2-a)/2 + P(l+b)]$$

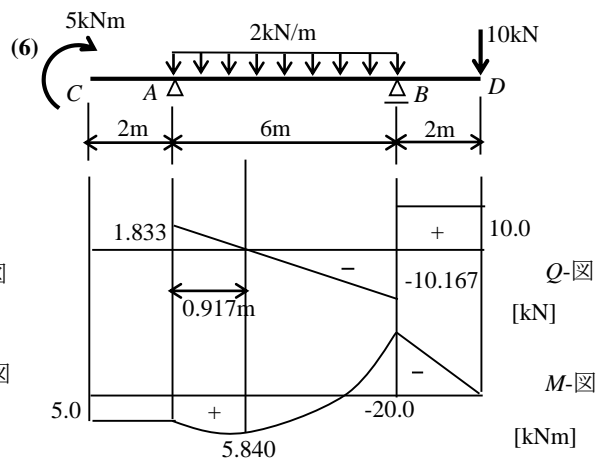


$$R_A = \frac{M}{l} = -R_B$$



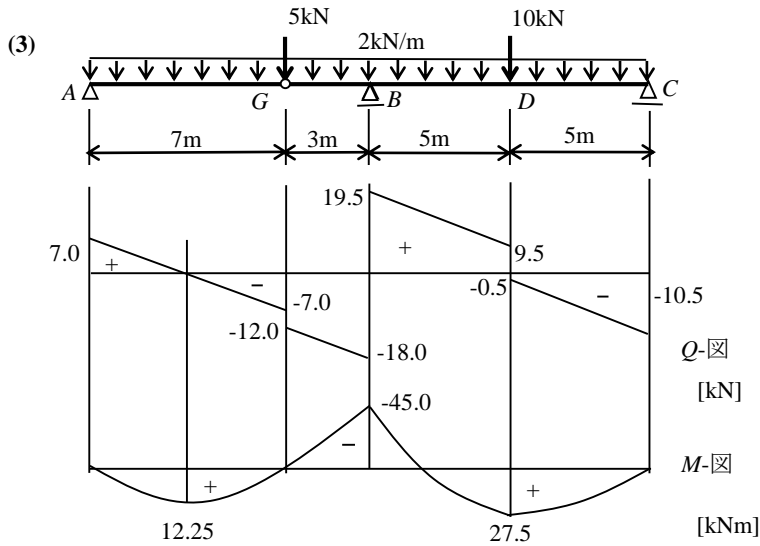
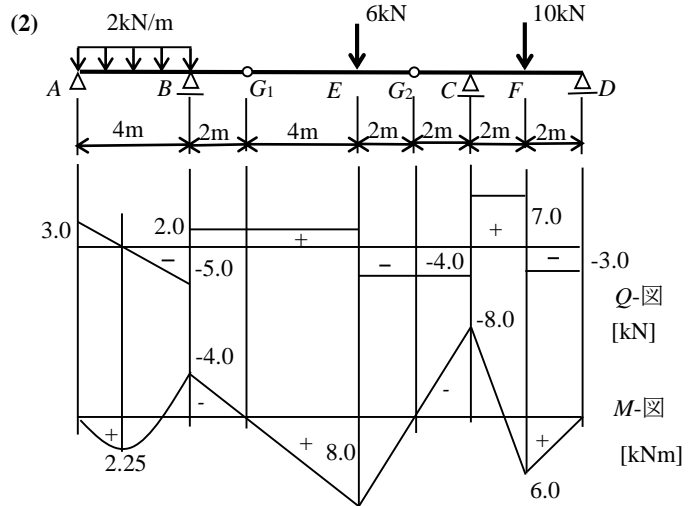
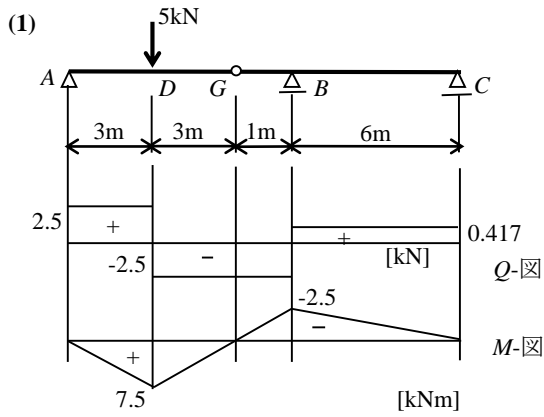
$$R_A = \frac{1}{l} \{ qa(a/2+l) + Pl/2 \}$$

$$R_B = \frac{1}{l} \{ -qa^2/2 + Pl/2 \}$$

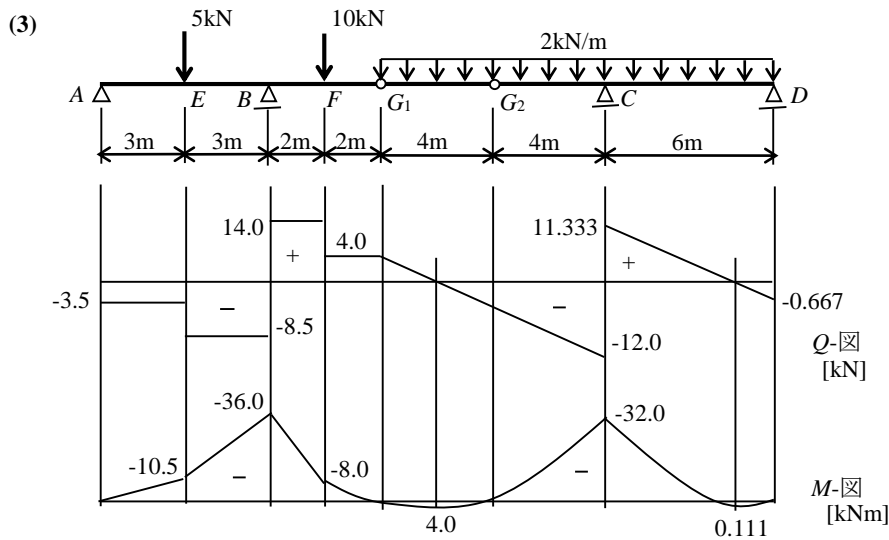


$$R_A = 1.833\text{kN}, \quad R_B = 20.167\text{kN}$$

[問題 5.5]



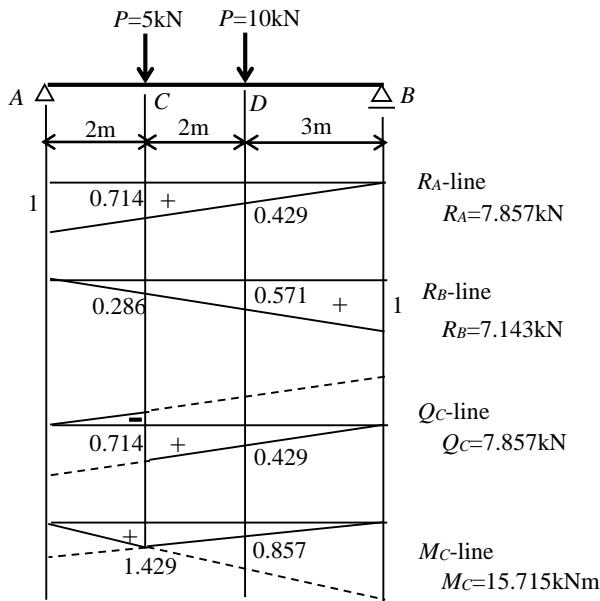
第 2 章 静定ばり



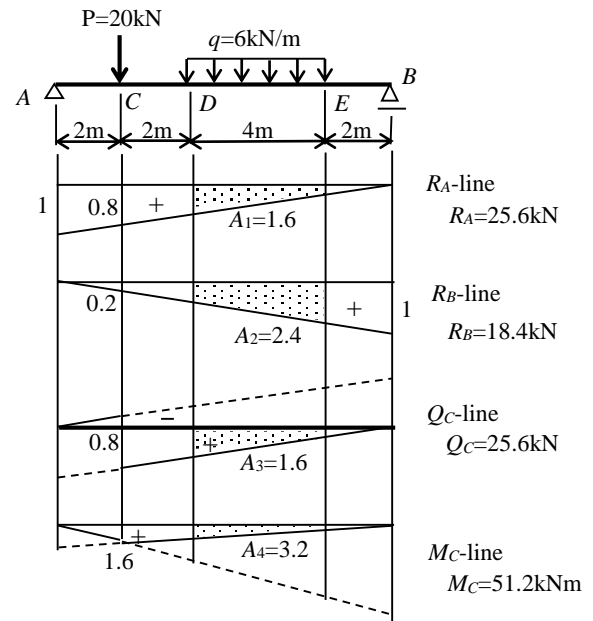
6. はりの影響線

[問題 6.1]

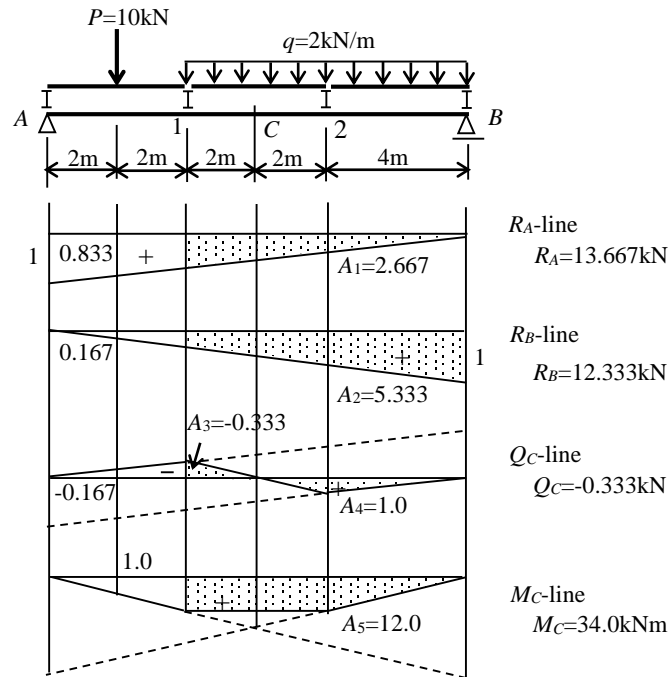
(1)



(2)

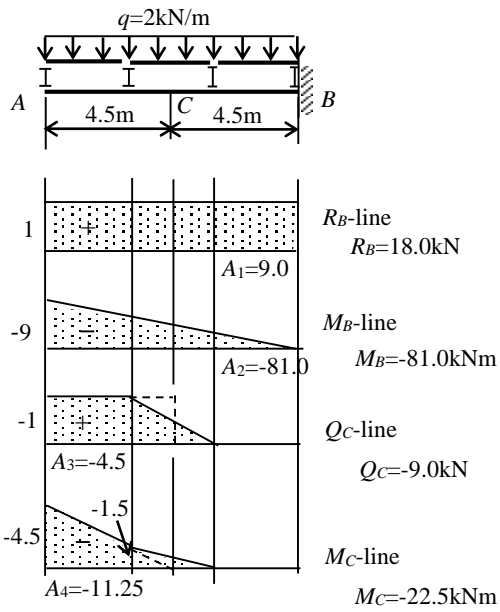


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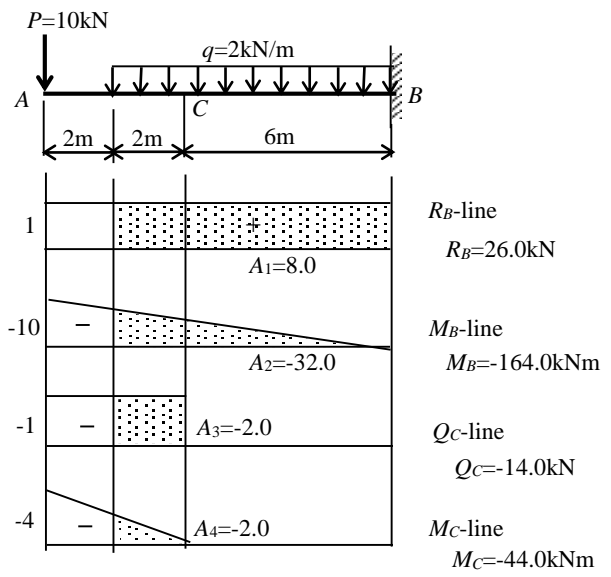


[問題 6.2]

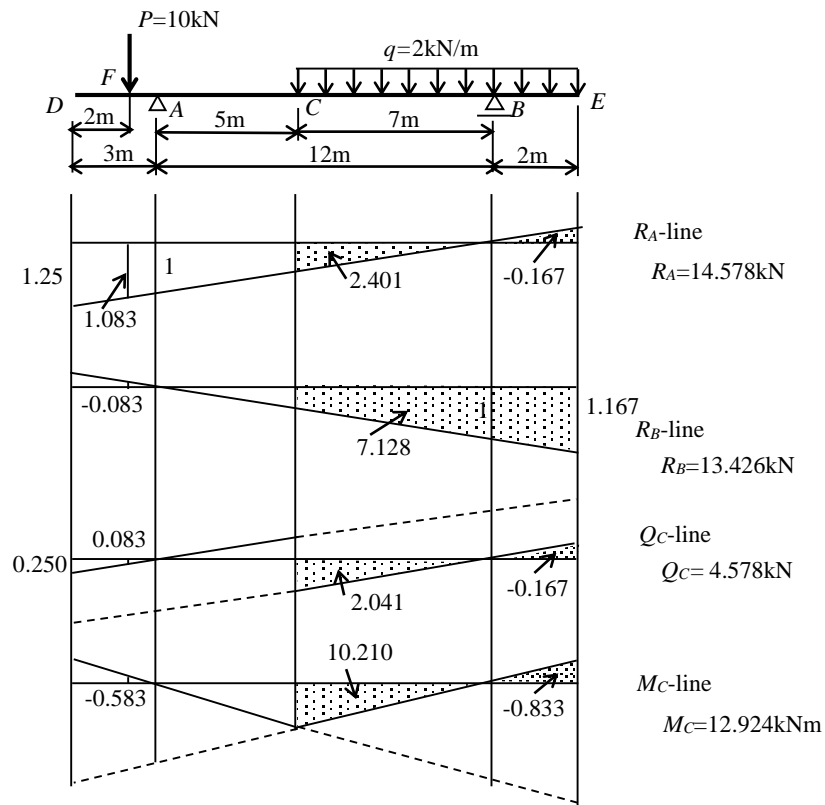
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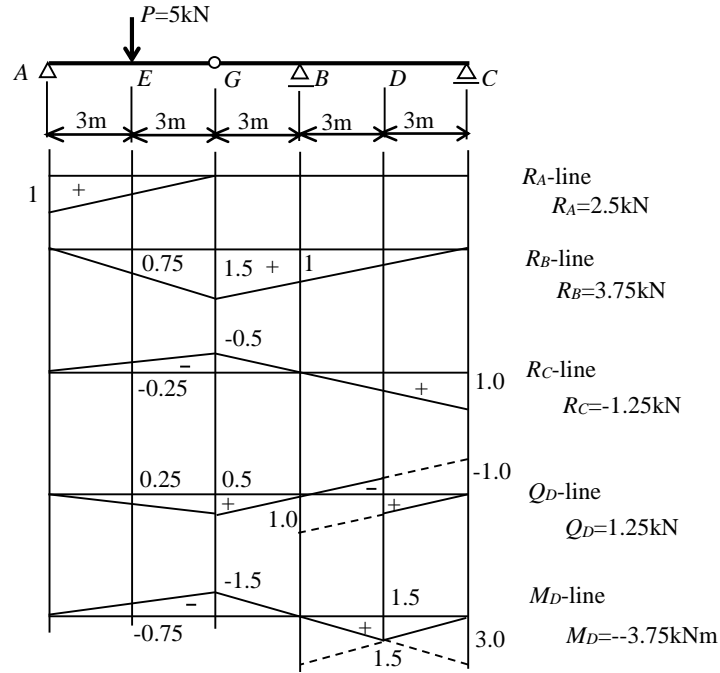
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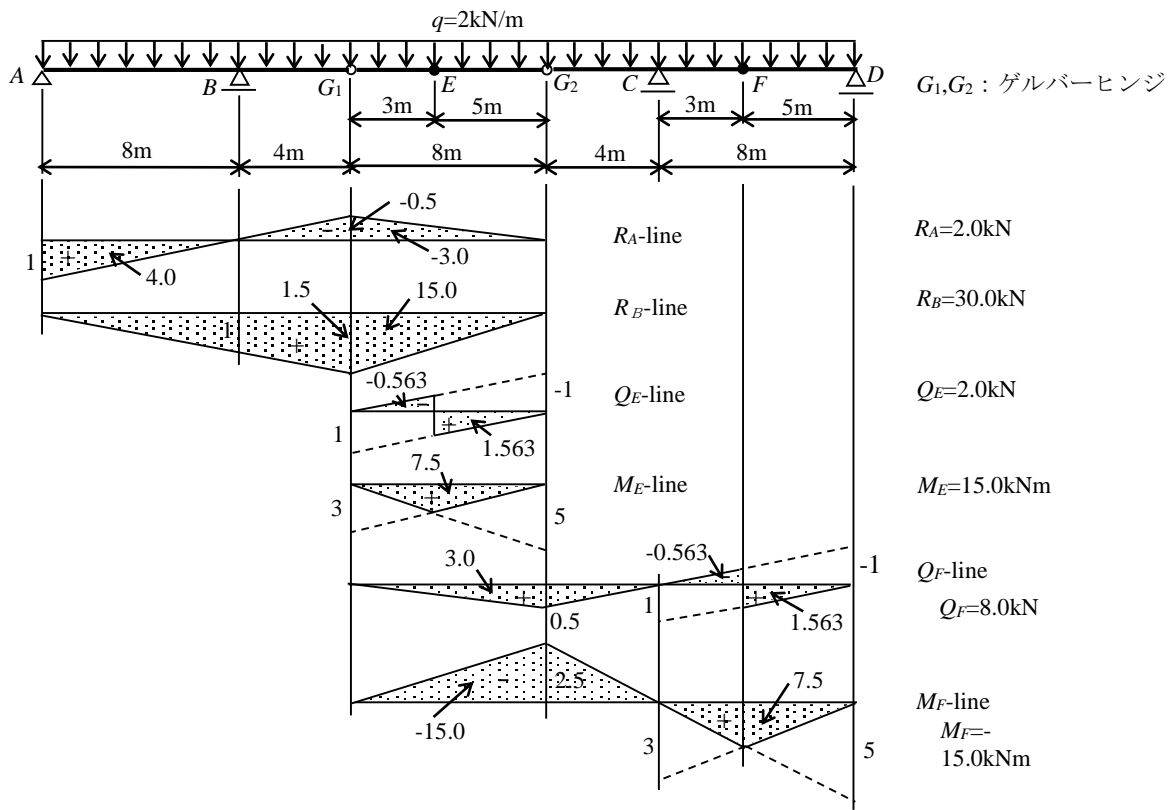
[問題 6.3]



[問題 6.4]



[問題 6.5]



7. 部材断面の性質

[問題 7.1]

断面積： $A=ab$, 微小面積： $dA=bdx$

$$y \text{ 軸に対する断面 1 次モーメント } G_y = \int x dA = \int_0^a bxdx = \frac{a^2b}{2}$$

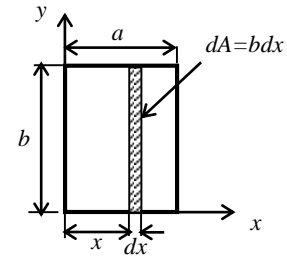


図 7.2

[問題 7.2]

$A = \frac{1}{2}ab$, x 点の長さ $b' = \frac{b}{a}(a-x)$ であるから

$$dA = b' \cdot dx = \frac{b}{a}(a-x)dx$$

$$G_y = \int x dA = \int_0^a \frac{b}{a}(a-x)x dx = \frac{a^2b}{6}$$

$$x_0 = \frac{G_y}{A} = \left(\frac{a^2b}{6} \right) / \left(\frac{ab}{2} \right) = \frac{a}{3}$$

すなわち, y 軸から 3 分の 1 の点にある.

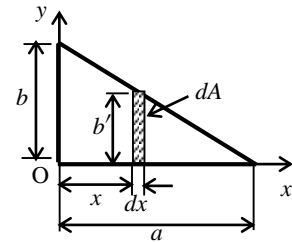


図 7.9

[問題 7.3]

(1) $y_0 = \frac{(60 \times 20) \cdot 50 + (30 \times 40) \cdot 20}{(60 \times 20) + (30 \times 40)} = 35\text{mm}$

(2) $x_0 = \frac{160 \cdot 10 + 160 \cdot 40}{160 + 160} = 25\text{mm}$, $y_0 = \frac{160 \cdot 60 + 160 \cdot 10}{160 + 160} = 35\text{mm}$

(3) $x_0 = \frac{4 \cdot 2 + 5 \cdot 1.5 + 2.5 \cdot 2.333}{4 + 5 + 2.5} = 1.855\text{m}$, $y_0 = \frac{4 \cdot 0.5 + 5 \cdot 3.5 + 2.5 \cdot 2.667}{4 + 5 + 2.5} = 2.275\text{m}$

[問題 7.4]

(1) $I_{x_1} = \frac{bh^3}{12}$, $I_{x_2} = \frac{bh^3}{12} + \frac{h^2}{4} \times bh = \frac{bh^3}{3}$, $I_{x_3} = \frac{bh^3}{12} + h^2 \times bh = \frac{13bh^3}{12}$

(2) すべて $I_x = 1834.17 \times 10^4 (\text{mm}^4)$

(a) $I_x = \frac{140 \cdot 130^3}{12} - 2 \times \frac{60 \cdot 90^3}{12} = 1834.17 \times 10^4 \text{cm}^4$ (b) $I_x = \frac{140 \cdot 130^3}{12} - \frac{120 \cdot 90^3}{12} = 1834.17 \times 10^4 \text{cm}^4$

(c) $I_x = \frac{140 \cdot 130^3}{12} - \frac{120 \cdot 90^3}{12} = 1834.17 \times 10^4 \text{mm}^4$

(3) (a) $A = 60 \times 20 + 30 \times 40 = 2400 \text{cm}^2$, $y_0 = \frac{1200 \times 50 + 1200 \times 20}{1200 + 1200} = 35\text{mm}$,

$$I_x = \frac{60 \times 20^3}{12} + (50 - 35)^2 \times 1200 + \frac{30 \times 40^3}{12} + (35 - 20)^2 \times 1200 = 740000 \text{mm}^4$$

(b) $A = 2(40 \times 100 - 30 \times 80) + (10 \times 100) = 4200 \text{mm}^2$

$G_1 = 50 \times (100 \times 40) - 50 \times (30 \times 80) = 80000 \text{mm}^3$, $G_2 = 105 \times (10 \times 100) = 105000 \text{mm}^3$,

$\therefore G_x = 2 \times G_1 + G_2 = 265000 \text{mm}^3$

$y_0 = \frac{G_x}{A} = \frac{265000}{4200} = 63.1 \text{mm}$

$$I_1 = 2 \left\{ \left(\frac{40 \times 100^3}{12} - \frac{30 \times 80^3}{12} \right) + 13.1^2 \times 1600 \right\} = 465.58 \times 10^4 \text{mm}^4,$$

$$I_2 = \frac{100 \times 10^3}{12} + 41.9^2 \times (10 \times 100) = 176.39 \times 10^4 \text{mm}^4$$

$I_{x_1} = I_1 + I_2 = 641.97 \times 10^4 \text{mm}^4$

(4)

$A_1 = 3 \times 15 = 45 \text{cm}^2$, $A_2 = 12 \times 4 = 48 \text{cm}^2$, $A_3 = 5 \times 15 = 75 \text{cm}^2$, $\therefore A = 168 \text{cm}^2$

$$G_1 = 7.5 \times A_1 = 337.5\text{cm}^3, \quad G_2 = 2 \times A_2 = 96\text{cm}^3, \quad \therefore G_3 = 7.5 \times A_3 = 562.5\text{cm}^3, \quad G_x = 996\text{cm}^3$$

$$y_0 = \frac{G_x}{A} = \frac{996}{168} = 5.93\text{cm}$$

$$I_1 = \frac{3 \times 15^3}{12} + 7.5^2 \times 45 = 3375\text{cm}^4, \quad I_2 = \frac{12 \times 4^3}{12} + 2^2 \times 48 = 256\text{cm}^4,$$

$$I_3 = \frac{5 \times 15^3}{12} + 7.5^2 \times 75 = 5625\text{cm}^4, \quad \therefore I_x = 9256\text{cm}^4, \quad I_G = 9256 - 5.93^2 \times 168 = 3348.30\text{cm}^4$$

[問題 7.5] (1) $I_{xy} = x_0 y_0 A = 0 \cdot \frac{b}{2} \cdot A = 0$, (あるいは $I_{xy} = \int xy dA = \int_{-a/2}^{a/2} x dx \int_0^b y dy = 0$)

(2) $I_{xy} = x_0 y_0 A = -\frac{a}{2} \cdot \frac{b}{2} \cdot ab = -\frac{a^2 b^2}{4}$,

$$\left(\text{あるいは } I_{xy} = \int xy dA = \int_0^b y dy \int_{-a}^0 x dx = \frac{b^2}{2} \left[\frac{x^2}{2} \right]_{-a}^0 = -\frac{a^2 b^2}{4} \right)$$

[問題 7.6]

$$I_u = \int v^2 dA = \int (y \cos \theta - x \sin \theta)^2 dA$$

$$= \int y^2 \cos^2 \theta dA - \int xy \cdot 2 \cos \theta \sin \theta dA + \int x^2 \sin^2 \theta dA$$

$$= I_x \cos^2 \theta + I_y \sin^2 \theta - I_{xy} \sin 2\theta = \frac{I_x + I_y}{2} + \frac{I_x - I_y}{2} \cos 2\theta - I_{xy} \sin 2\theta$$

$$I_v = \int u^2 dA = \int (x \cos \theta + y \sin \theta)^2 dA$$

$$= \int x^2 \cos^2 \theta dA + \int xy \cdot 2 \sin \theta \cos \theta dA + \int y^2 \sin^2 \theta dA$$

$$= I_x \cos^2 \theta + I_x \sin^2 \theta + I_{xy} \sin 2\theta = \frac{I_x + I_y}{2} - \frac{I_x - I_y}{2} \cos 2\theta + I_{xy} \sin 2\theta$$

$$I_{uv} = \int uv dA = \int (x \cos \theta + y \sin \theta)(y \cos \theta - x \sin \theta) dA$$

$$= \int xyc \cos^2 \theta dA - \int x^2 c \cos \theta \sin \theta dA + \int y^2 s \sin \theta \cos \theta dA - \int xys \sin^2 \theta dA$$

$$= \frac{1}{2} I_x \sin 2\theta - \frac{1}{2} I_y \sin 2\theta + \int xy(c \cos^2 \theta - s \sin^2 \theta) dA = \frac{1}{2} I_x \sin 2\theta - \frac{1}{2} I_y \sin 2\theta + I_{xy} \cos 2\theta$$

$$= \frac{I_x - I_y}{2} \sin 2\theta + I_{xy} \cos 2\theta$$

注) 以上よりさらに次の関係が得られる.

$$\frac{\partial I_u}{\partial \theta} = 2I_x \cos \theta (-\sin \theta) + 2I_y \sin \theta \cos \theta - 2I_{xy} \cos 2\theta = -I_x \sin 2\theta + I_y \sin 2\theta - 2I_{xy} \cos 2\theta$$

$$\frac{\partial I_v}{\partial \theta} = 2I_x \sin \theta \cos \theta + 2I_y \cos \theta (-\sin \theta) + 2I_{xy} \cos 2\theta = I_x \sin 2\theta - I_y \sin 2\theta + 2I_{xy} \cos 2\theta$$

$$\therefore -\frac{\partial I_u}{\partial \theta} = \frac{\partial I_v}{\partial \theta} = 2I_{uv}$$

[問題 7.7] 式(7.22)を3元1次の連立方程式として解く. 第1式と第2式を加え合わせると

$$I_x + I_y = I_u + I_v \tag{1}$$

第3式より $I_{xy} = \frac{I_{uv}}{\cos 2\theta} - \frac{I_x - I_y}{2} \tan 2\theta$ (2)

式(7.22)の第1式より第2式を引くと

$$I_u - I_v = (I_x - I_y) \cos 2\theta - 2I_{xy} \sin 2\theta = (I_x - I_y) \cos 2\theta - 2I_{uv} \tan 2\theta + (I_x - I_y) \frac{\sin 2\theta}{\cos 2\theta}$$

$$= \frac{I_x - I_y}{\cos 2\theta} (\cos^2 2\theta + \sin^2 2\theta) - 2I_{uv} \tan 2\theta = \frac{I_x - I_y}{\cos 2\theta} - 2I_{uv} \tan 2\theta$$

ゆえに

$$I_x - I_y = (I_u - I_v) \cos 2\theta + 2I_{uv} \sin 2\theta \tag{3}$$

式(1)と式(3)を加え合わせると、式(7.23)の第1式が、式(1)から式(3)を引くと第2式が得られる。
式(2)に式(3)を代入して変形する。

$$\begin{aligned} I_{xy} &= \frac{I_{uv}}{\cos 2\theta} - \frac{I_x - I_y}{2} \tan 2\theta = \frac{I_{uv}}{\cos 2\theta} - \frac{1}{2} [(I_u - I_v) \cos 2\theta + 2I_{uv} \sin 2\theta] \tan 2\theta \\ &= \frac{I_{uv}}{\cos 2\theta} - \frac{I_u - I_v}{2} \sin 2\theta - I_{uv} \frac{\sin^2 2\theta}{\cos 2\theta} = \frac{I_{uv}}{\cos 2\theta} - \frac{I_u - I_v}{2} \sin 2\theta - \frac{I_{uv}}{\cos 2\theta} + I_{uv} \cos 2\theta \\ &= -\frac{I_u - I_v}{2} \sin 2\theta + I_{uv} \cos 2\theta \end{aligned}$$

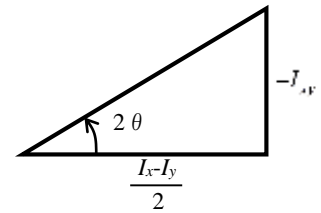
これは、式(7.23)の第3式である。

[別解] 式(7.22)の x, y と u, v を入れ替え、 θ のかわりに $-\theta$ とおけばよい。

[問題 7.8] 式(7.22)の第3式において $I_{uv}=0$ とおくと、式(7.24)

$$\tan 2\theta = -\frac{I_{xy}}{\frac{I_x - I_y}{2}}$$

が得られる。この式は、右図の関係を表している。したがって



$$\sin 2\theta = \frac{-I_{xy}}{\sqrt{\left(\frac{I_x - I_y}{2}\right)^2 + I_{xy}^2}}, \quad \cos 2\theta = \frac{\frac{I_x - I_y}{2}}{\sqrt{\left(\frac{I_x - I_y}{2}\right)^2 + I_{xy}^2}}$$

この関係を式(3.22)に適用すればよい。 $I_{uv}=0$ となる I_u を I_1 、 I_v を I_2 とすると

$$\begin{aligned} I_1 &= \frac{I_x + I_y}{2} + \frac{I_x - I_y}{2} \cos 2\theta - I_{xy} \sin 2\theta = \frac{I_x + I_y}{2} + \frac{I_x - I_y}{2} \frac{\frac{I_x - I_y}{2}}{\sqrt{\left(\frac{I_x - I_y}{2}\right)^2 + I_{xy}^2}} - I_{xy} \frac{-I_{xy}}{\sqrt{\left(\frac{I_x - I_y}{2}\right)^2 + I_{xy}^2}} \\ &= \frac{I_x + I_y}{2} + \frac{\left(\frac{I_x - I_y}{2}\right)^2 + I_{xy}^2}{\sqrt{\left(\frac{I_x - I_y}{2}\right)^2 + I_{xy}^2}} = \frac{I_x + I_y}{2} + \sqrt{\left(\frac{I_x - I_y}{2}\right)^2 + I_{xy}^2} \\ I_1 &= \frac{I_x + I_y}{2} - \frac{I_x - I_y}{2} \cos 2\theta + I_{xy} \sin 2\theta = \frac{I_x + I_y}{2} - \frac{I_x - I_y}{2} \frac{\frac{I_x - I_y}{2}}{\sqrt{\left(\frac{I_x - I_y}{2}\right)^2 + I_{xy}^2}} + I_{xy} \frac{-I_{xy}}{\sqrt{\left(\frac{I_x - I_y}{2}\right)^2 + I_{xy}^2}} \\ &= \frac{I_x + I_y}{2} - \frac{\left(\frac{I_x - I_y}{2}\right)^2 + I_{xy}^2}{\sqrt{\left(\frac{I_x - I_y}{2}\right)^2 + I_{xy}^2}} = \frac{I_x + I_y}{2} - \sqrt{\left(\frac{I_x - I_y}{2}\right)^2 + I_{xy}^2} \end{aligned}$$

[問題 7.9]

(1) $x_0 = \frac{16 \times 1 + 16 \times 4}{16 + 16} = 2.5(\text{cm}), \quad y_0 = \frac{16 \times 6 + 16 \times 1}{16 + 16} = 3.5(\text{cm})$

(2) $I_x = \frac{2 \times 8^3}{12} + 6^2 \times 16 + \frac{8 \times 2^3}{12} + 1^2 \times 16 = 682.67(\text{cm}^4)$

$I_y = \frac{8 \times 2^3}{12} + 1^2 \times 16 + \frac{2 \times 8^3}{12} + 4^2 \times 16 = 362.67(\text{cm}^4)$

$I_{xy} = 1 \times 6 \times 16 + 4 \times 1 \times 16 = 160(\text{cm}^4)$

(3) $I_u = 682.67 - 3.5^2 \times (16 + 16) = 290.67(\text{cm}^4)$

$I_v = 362.67 - 2.5^2 \times (16 + 16) = 162.67(\text{cm}^4)$

$I_{uv} = 160 - 3.5 \times 2.5 \times (16 + 16) = -120(\text{cm}^4)$

$$(4) \quad \tan 2\theta = -\frac{I_{uv}}{\frac{I_u - I_v}{2}} = -\frac{-120}{64} = 1.875, \quad \therefore \theta = 30^\circ 57' 49''$$

$$I_{1,2} = \frac{I_u + I_v}{2} \pm \sqrt{\left(\frac{I_u - I_v}{2}\right)^2 + I_{uv}^2} \quad \text{より } I_1 = 362.67(\text{cm}^4), \quad I_2 = 90.67(\text{cm}^4)$$

[問題 7.10]

(1) P.7-7 注意事項より求めよ.

$$(a) \quad I = \frac{bh^3}{12}, \quad W = \frac{I}{h/2} = \frac{bh^2}{6}, \quad r_x = \sqrt{\frac{I}{A}} = \frac{h}{2\sqrt{3}}, \quad K = \frac{W}{A} = \frac{h}{6}$$

$$(b) \quad I = \frac{bh^3}{36}, \quad W_c = \frac{I}{2h/3} = \frac{bh^2}{24}, \quad W_t = \frac{I}{h/3} = \frac{bh^2}{12}, \quad r_x = \sqrt{\frac{I}{A}} = \frac{h}{3\sqrt{2}}, \quad K_t = \frac{W_c}{A} = \frac{h}{12}, \quad K_c = \frac{W_t}{A} = \frac{h}{6}$$

$$(c) \quad I = \frac{\pi r^4}{4}, \quad W = \frac{I}{r} = \frac{\pi r^3}{4}, \quad r_x = \sqrt{\frac{I}{A}} = \frac{r}{2}, \quad K = \frac{W}{A} = \frac{r}{4}$$

(2) 問題 7.4(3)a を用いる.

$$W_c = \frac{74}{2.5} = 29.6\text{cm}^3, \quad W_t = \frac{74}{3.5} = 21.143\text{cm}^3, \quad r = \sqrt{\frac{74}{24}} = 1.756\text{cm},$$

$$k_c = \frac{21.143}{24} = 0.881\text{cm}, \quad k_t = \frac{29.6}{24} = 1.233\text{cm}$$

(3) (a) 問題 7.9 を使用する.

$$y_0 = 3.5\text{cm}, \quad I_x = 290.67\text{cm}^4, \quad W_1 = \frac{290.67}{6.5} = 44.72\text{cm}^3, \quad W_2 = \frac{290.67}{3.5} = 83.05\text{cm}^3$$

$$(b) \quad A = 5 \times 1 + \frac{1}{2} \times 1 \times 5 + 4 = 11.5\text{m}^2, \quad y_0 = \frac{4 \times 0.5 + 5 \times 3.5 + 2.5 \times 2.667}{4 + 5 + 2.5} = 2.275\text{m}$$

$$I_x = \frac{1 \times 5^3}{12} + (3.5 - 2.275)^2 \times (1 \times 5) + \frac{1 \times 5^3}{36} + \left(\frac{5}{3} + 1 - 2.275\right)^2 \times \left(\frac{1}{2} \times 1 \times 5\right) \\ + \frac{4 \times 1^3}{12} + (2.275 - 0.5)^2 \times (4 \times 1) = 10.42 + 7.5 + 3.47 + 0.38 + 0.33 + 12.60 = 34.70\text{m}^4$$

$$W_c = \frac{34.70}{3.725} = 9.32\text{m}^3, \quad W_t = \frac{34.70}{2.275} = 15.25\text{m}^3$$

$$(4) \quad A = 14 \times 13 - 12 \times 9 = 74\text{cm}^2$$

$$I_x = \frac{14 \times 13^3}{12} - \frac{12 \times 9^3}{12} = 1834.17\text{cm}^4$$

$$r_x = \sqrt{\frac{I_x}{A}} = \sqrt{\frac{1834.17}{74}} = \sqrt{24.78} = 4.98\text{cm}$$

$$x_0 = \frac{13 \times 14 \times 7 - 12 \times 9 \times 8}{74} = \frac{1274 - 864}{74} = 5.54\text{cm}$$

$$I_y = 2 \left\{ \frac{2 \times 14^3}{12} + (7 - 5.54)^2 \times 14 \times 2 \right\} + \frac{9 \times 2^3}{12} + (5.54 - 1)^2 \times 9 \times 2 \\ = 2(457.33 + 59.68) + 6 + 371.01 = 1411.03\text{cm}^4$$

$$r_y = \sqrt{\frac{I_y}{A}} = \sqrt{\frac{1411.03}{74}} = \sqrt{19.07} = 4.37\text{cm}$$

8. 応力とひずみ

$$[\text{問題 8.2}] \quad \Delta l = \frac{Pl}{EA} = \frac{5 \times 1000}{2.0 \times 10^5 \times \frac{3.14 \times 10^2}{4}} = 3.18 \times 10^{-4} \text{ mm}$$

$$[\text{問題 8.3}] \quad \sigma = \frac{P}{A} = \frac{20000}{\pi \times 20^2 / 4} = 63.69 \text{ N/mm}^2, \quad E = \frac{\sigma l}{\Delta l} = \frac{63.69 \times 2000}{0.63} = 2.02 \times 10^5 \text{ N/mm}^2$$

$$[\text{問題 8.4}] \quad \sigma = 2.0 \times 10^5 \times 0.000001 \times (30 - 10) = 4 \text{ N/mm}^2$$

$$[\text{問題 8.5}] \quad A = \frac{3.14 \times 22}{4} = 379.94 \text{ mm}^2, \quad \tau = \frac{P}{A} = \frac{1500}{379.94} = 3.95 \text{ N/mm}^2$$

[問題 8.6] 3つの部材は同じ大きさのひずみを生じるから

$$\varepsilon = \frac{P_1}{E_1 A_1} = \frac{P_2}{E_2 A_2} = \frac{P_3}{E_3 A_3}$$

一方、力の釣合いから $P = P_1 + P_2 + P_3$

$$\text{であるから} \quad \varepsilon = \frac{P_1}{E_1 A_1} = \frac{P_2}{E_2 A_2} = \frac{P_3}{E_3 A_3} = \frac{P_1 + P_2 + P_3}{E_1 A_1 + E_2 A_2 + E_3 A_3} = \frac{P}{E_1 A_1 + E_2 A_2 + E_3 A_3}$$

$$\text{したがって} \quad P_1 = \frac{PE_1 A_1}{E_1 A_1 + E_2 A_2 + E_3 A_3}, \quad P_2 = \frac{PE_2 A_2}{E_1 A_1 + E_2 A_2 + E_3 A_3}, \quad P_3 = \frac{PE_3 A_3}{E_1 A_1 + E_2 A_2 + E_3 A_3}$$

すなわち、各部材の力はその部材の EA に比例した力が働いている。

[問題 8.7] コンクリートの断面積: $A_c = 250 \times 250 = 62500 \text{ mm}^2$,

$$\text{鉄筋の断面積} : A_s = 3.14 \times 22^2 / 4 \times 4 = 1519.76 \text{ mm}^2$$

ここで $n = \frac{E_s}{E_c} = 15$ であるから

$$\sigma_c = \frac{PE_c}{E_c A_c + E_s A_s} = \frac{P}{A_c + n A_s} = \frac{50000}{62500 + 15 \times 1519.76} = 0.586 \text{ N/mm}^2$$

$$\sigma_s = n \sigma_c = 15 \times 0.586 = 8.79 \text{ N/mm}^2$$

[問題 8.8] 2つの条件がある. 1つは力の釣合いから $\sum V = 0: R_1 + R_2 = P$ (1)

つぎに、部材 AC の伸びは部材 CB の縮みに等しい. すなわち $\Delta l_1 = \Delta l_2$ (2)

$$\text{ここで} \quad \Delta l_1 = \frac{R_1 l_1}{E_1 A_1}, \quad \Delta l_2 = \frac{R_2 l_2}{E_2 A_2} \quad (3)$$

$$\text{式(3)を式(2)に代入して} \quad \frac{R_1 l_1}{E_1 A_1} = \frac{R_2 l_2}{E_2 A_2} \quad (4)$$

$$\text{式(1)と式(4)より} \quad R_1 = \frac{E_1 A_1 l_2}{E_1 A_1 l_2 + E_2 A_2 l_1} P, \quad R_2 = \frac{E_2 A_2 l_1}{E_1 A_1 l_2 + E_2 A_2 l_1} P \quad (5)$$

[問題 8.9] 下底より x の点の微小要素 dx について考える. x 点に働く応力 σ_x はその重さ $Ax \cdot \omega$ によって

$$\sigma_x = \frac{Ax \cdot \omega}{A} = x\omega$$

応力 σ_x による微小要素 dx の伸び量 Δdx は、Hooke の法則 $\varepsilon = \frac{\Delta dx}{dx}$ より

$$\Delta dx = \frac{\sigma_x}{E} dx = \frac{x\omega}{E} dx$$

したがって、全体の伸び量は、これを $x=0$ から l まで積分すればよい.

$$\Delta l = \int_0^l \Delta dx = \frac{\omega}{E} \int_0^l x dx = \frac{\omega}{E} \left[\frac{x^2}{2} \right]_0^l = \frac{\omega l^2}{2E} = \frac{l}{EA} \frac{W}{2}$$

ここで、 $W = Al\omega$ は全自重を表す. すなわち、自重を無視して下端に $W/2$ の引張り力を作用させたときの伸びと等しい.

[問題 8.10]

部材 1 と部材 2 には共に $P=2\text{kN}$ の力が作用する。ゆえに

$$\Delta l = \sum \frac{Pl}{EA} = \frac{P}{E} \left(\frac{l_1}{A_1} + \frac{l_2}{A_2} \right) = \frac{2 \times 10^3}{2.0 \times 10^5} \left(\frac{2000}{100 \times 100} + \frac{1000}{50 \times 50} \right) = 0.006 \text{ mm}$$

9. はりの応力度

[問題 9.1] (1) $\sigma = \frac{M}{I} y = \frac{1000}{\frac{12}{bh^3}} \times \frac{h}{2} = 18.75 \times 10^4 \text{ N/m}^2$

(2) $\sigma = \frac{M}{I} y = \frac{1000}{\frac{\pi d^4}{64}} \times \frac{d}{2} = 127.4 \times 10^4 \text{ N/m}^2$

(3) $W_c = \frac{I}{\frac{2}{3}h} = \frac{bh^2}{24} = 2.0 \times 10^{-3} \text{ m}^3$, $W_t = \frac{I}{\frac{1}{3}h} = \frac{bh^2}{12} = 4.0 \times 10^{-3} \text{ m}^3$

$$\therefore \sigma_c = -50.0 \text{ N/m}^2, \quad \sigma_t = 25.0 \text{ N/m}^2$$

[問題 9.2] $y_0 = 35 \text{ mm}$, $I = 740\,000 \text{ mm}^4$

$$\sigma_c = -\frac{M}{I} y_c = -\frac{200\,000}{740\,000} \times 25 = -6.76 \text{ N/m}^2$$

$$\sigma_t = \frac{M}{I} y_t = \frac{200\,000}{740\,000} \times 35 = 9.46 \text{ N/m}^2$$

[問題 9.3] フランジ部分に対しては

$$G_1 = A_1 y_1 = 60 \times 20 \times 15 = 18\,000 \text{ mm}^3, \quad \tau_1 = \frac{QG_1}{bI} = \frac{2\,000 \times 18\,000}{60 \times 740\,000} = 0.81 \text{ N/mm}^2$$

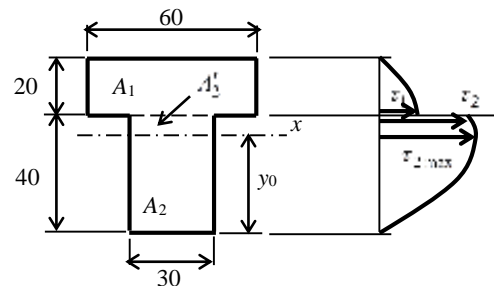
ウェブ部分に対しては

$$G_2 = A_1 y_1 + A_2' y_2 = (60 \times 20) \times 15 + (30 \times 5) \times 2.5 = 18.375 \times 10^3 \text{ mm}^3$$

$$\tau_2 = \frac{QG_1}{bI} = \frac{2\,000 \times 18.0 \times 10^3}{30 \times 740\,000} = 1.62 \text{ N/mm}^2$$

$$\tau_{2\text{max}} = \frac{QG_2}{bI} = \frac{2\,000 \times 18.375 \times 10^3}{30 \times 740\,000} = 1.66 \text{ N/mm}^2$$

$$\frac{\tau_1}{\tau_2} = \frac{0.81}{1.62} = \frac{1}{2} = \frac{3}{6}$$



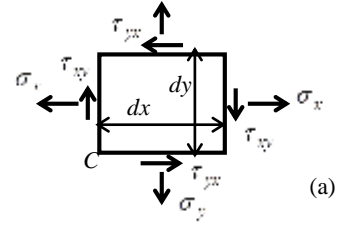
$$y_0 = 35 \text{ mm}$$

$$I = 740\,000 \text{ mm}^4$$

10. モールの応力円

[問題 10.1] 図 4.17(a)において点 C でモーメント釣合いを考える。
奥行き b とする。

$$\sum M_C = 0: \tau_{xy} \cdot dy \cdot b \cdot dx - \tau_{yx} \cdot dx \cdot b \cdot dy = 0, \therefore \tau_{xy} = \tau_{yx}$$



[問題 10.2] 各辺の微小面積を dA_x, dA_y, dA_n とすると

$$dA_y = dA_n \cos \phi, \quad dA_x = dA_n \sin \phi$$

$$\sum H = 0:$$

$$\sigma_n \cos \phi \cdot dA_n + \tau_{uv} \sin \phi \cdot dA_n - \sigma_x dA_y + \tau_{xy} dA_x = 0$$

$$\sum V = 0:$$

$$\sigma_n \sin \phi \cdot dA_n - \tau_{uv} \cos \phi \cdot dA_n - \sigma_y dA_x + \tau_{xy} dA_y = 0$$

この 2 式より

$$\left. \begin{aligned} \sigma_n \cos \phi + \tau_{uv} \sin \phi - \sigma_x \cos \phi + \tau_{xy} \sin \phi &= 0 \\ \sigma_n \sin \phi - \tau_{uv} \cos \phi - \sigma_y \sin \phi + \tau_{xy} \cos \phi &= 0 \end{aligned} \right\} \quad (1)$$

$$(1)_1 \times \cos \phi + (1)_2 \times \sin \phi$$

$$\sigma_n = \sigma_x \cos^2 \phi + \sigma_y \sin^2 \phi - \tau_{xy} \sin \phi \cos \phi = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos 2\phi - \tau_{xy} \sin 2\phi$$

$$(1)_1 \times \sin \phi - (1)_2 \times \cos \phi$$

$$\tau_{uv} = (\sigma_x - \sigma_y) \sin \phi \cos \phi - \tau_{xy} (\sin^2 \phi - \cos^2 \phi) = \frac{\sigma_x - \sigma_y}{2} \sin 2\phi + \tau_{xy} \cos 2\phi$$

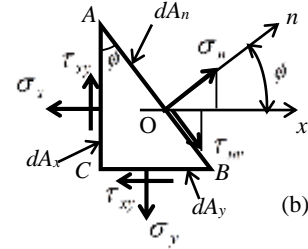


図 4.17

[問題 10.3] $\phi = \phi + \pi/2$ を式(4.26)に代入し, $\sin 2\phi = -\sin 2\phi$, $\cos 2\phi = -\cos 2\phi$ を用いる。

[問題 10.4]

- (1) $\sigma_u = 16.25 \text{ N/mm}^2$, $\tau_{uv} = 6.49 \text{ N/m}^2$
- (2) $\sigma_u = 13.75 \text{ N/mm}^2$, $\tau_{uv} = 10.81 \text{ N/m}^2$
- (3) $\sigma_u = -13.75 \text{ N/mm}^2$, $\tau_{uv} = -10.81 \text{ N/m}^2$

[問題 10.5] 図 4.18(b)より

$$\sigma_u = OC + CH \cos(\alpha + 2\phi) = OC + CH \cos \theta \cos 2\phi - CH \sin \theta \sin 2\phi$$

$$= \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos 2\phi - \tau_{xy} \sin 2\phi$$

$$\tau_{uv} = CH \sin(\alpha + 2\phi) = CH \cos \theta \sin 2\phi - CH \sin \theta \cos 2\phi$$

$$= \frac{\sigma_x - \sigma_y}{2} \sin 2\phi + \tau_{xy} \cos 2\phi$$

[問題 10.6] 問題 4.15 より

$$\sigma_u = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos 2\phi - \tau_{xy} \sin 2\phi = 11.16 \text{ N/mm}^2,$$

$$\tau_{uv} = \frac{\sigma_x - \sigma_y}{2} \sin 2\phi + \tau_{xy} \cos 2\phi = 12.31 \text{ N/mm}^2$$

式(3.34)より

$$\sigma_{1,2} = \frac{\sigma_x + \sigma_y}{2} \pm \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} = 20.35 \text{ N/mm}^2, \quad -5.35 \text{ N/mm}^2$$

$$\text{式(3.35)より} \quad \tan 2\alpha = -\frac{\tau_{xy}}{\frac{\sigma_x - \sigma_y}{2}} = -0.24 \quad (\text{モールの応力円は省略})$$

11. 弾性曲線によるはりのたわみ

[問題 11.1] 2階の微分方程式より求める.

$$x \text{ 点の曲げモーメントは } M_x = R_A x - \frac{q}{2l} x^2 \frac{x}{3} = \frac{q}{6} (lx - \frac{1}{l} x^3)$$

これを弾性曲線の微分方程式に代入して積分する. また, 簡単のため積分定数は積分の中に入れて計算し, 積分記号も省略する.

$$\begin{aligned} \frac{d^2 y}{dx^2} &= -\frac{M_x}{EI} = -\frac{q}{6EI} (lx - \frac{1}{l} x^3) \\ \theta &= \frac{dy}{dx} = -\frac{q}{6EI} \left(\frac{l}{2} x^2 - \frac{1}{4l} x^4 + C_1 \right), \\ y &= -\frac{q}{6EI} \left(\frac{l}{6} x^3 - \frac{1}{20l} x^5 + C_1 x + C_2 \right) \end{aligned}$$

境界条件を適用する

$$x=0: y=0 \text{ より } C_2=0, \quad x=l: y=0 \text{ より } C_1 = -\frac{7l^3}{60}$$

したがって y, θ は

$$y = -\frac{q}{360EI} (-3x^5 + 10l^2 x^3 - 7l^4 x), \quad \theta = \frac{dy}{dx} = -\frac{q}{360EI} (-15x^4 + 30l^2 x^2 - 7l^4)$$

$$\text{ここで } \theta_A = \frac{7ql^3}{360EI}, \quad \theta_B = -\frac{ql^3}{45EI}$$

最大たわみはたわみ角 $\theta=0$ より $15x^4 - 30l^2 x^2 + 7l^4 = 0$, これより $x = 0.519l$

これをたわみの式に代入して $y_{\max} = \frac{2.35ql^4}{360EI}$ を得る.

[別解] 4階の微分方程式より求める. 順次積分すると

$$\begin{aligned} \frac{d^4 y}{dx^4} &= \frac{q}{EI} x, & \frac{d^3 y}{dx^3} &= \frac{q}{2EI} x^2 + C_1 \\ \frac{d^2 y}{dx^2} &= \frac{q}{6EI} x^3 + C_1 x + C_2, & \frac{dy}{dx} &= \frac{q}{24EI} x^4 + \frac{C_1}{2} x^2 + C_2 x + C_3 \\ y &= \frac{q}{120EI} x^5 + \frac{C_1}{6} x^3 + \frac{C_2}{2} x^2 + C_3 x + C_4 \end{aligned}$$

境界条件を適用する

$$x=0: y=0 \rightarrow C_4=0, \quad x=0: M=0 \rightarrow C_2=0, \quad x=l: M=0 \rightarrow C_1 = -\frac{ql}{6EI},$$

$$x=l: y=0 \rightarrow C_3 = \frac{7ql^3}{360EI}$$

これより $y = -\frac{q}{360EI} (-3x^5 + 10l^2 x^3 - 7l^4 x)$ これは上に求めた結果と一致する.

[問題 11.2] x 点の曲げモーメント: $M_x = \frac{M_A}{l} (l-x)$

弾性曲線の微分方程式

$$\frac{d^2 y}{dx^2} = -\frac{M_x}{EI} = \frac{M_A}{EI} (x-l)$$

これを積分する.

$$\theta = \frac{dy}{dx} = \frac{M_A}{EI} \left(\frac{1}{2} x^2 - lx + C_1 \right), \quad y = \frac{M_A}{EI} \left(\frac{1}{6} x^3 - \frac{l}{2} x^2 + C_1 x + C_2 \right)$$

境界条件は $x=0: y=0 \rightarrow C_2=0, \quad x=l: y=0 \rightarrow C_1 = \frac{l^2}{3}$

ゆえに

$$\theta = \frac{M_A}{6EI}(3x^2 - 6lx + 2l^2), \quad y = \frac{M_A}{6EI}(x^3 - 3lx^2 + 2l^2x), \quad \text{また,} \quad \theta_A = \frac{M_A l}{3EI}, \quad \theta_B = -\frac{M_A l}{6EI}$$

[問題 11.3] 荷重より左のたわみを y_1 , 右のそれを y_2 とする.

$0 \leq x \leq a$

曲げモーメント: $M_x = -\frac{M}{l}x$

$$EI \frac{d^2 y_1}{dx^2} = \frac{M}{l}x$$

$$EI \frac{dy_1}{dx} = \frac{M}{2l}x^2 + C_1$$

$$EI y_1 = \frac{M}{6l}x^3 + C_1 x + C_2$$

境界条件: $x=0: y_1=0$

連続条件:

$$x=a: y_1 = y_2$$

$$x=a: \theta_1 = \theta_2$$

この4つの条件より $C_1 = \frac{M}{6l}(2l^2 + 3a^2 - 6la), \quad C_2 = 0, \quad D_1 = \frac{M}{6l}(2l^2 + 3a^2), \quad D_2 = -\frac{Ma^2}{2}$

ゆえに

$$\theta_1 = \frac{M}{6EI} \{ 3x^2 + (2l^2 + 3a^2 - 6la) \}$$

$$y_1 = \frac{M}{6EI} \{ x^3 + (2l^2 + 3a^2 - 6la)x \}$$

$$x=0: \theta_A = \frac{M}{6EI}(2l^2 + 3a^2 - 6la)$$

$$a = \frac{l}{2}: \theta_A = -\frac{Ml}{24EI}$$

$$x=a \text{ におけるたわみ } : y_{x=a} = \frac{Ma}{3EI}(l^2 + 2a^2 - 3la)$$

$$x=a \text{ におけるたわみ角 } : \theta_{x=a} = \frac{M}{3EI}(l^2 + 3a^2 - 3la)$$

$$a=b=\frac{l}{2} \text{ のとき } : y_{\frac{l}{2}} = 0, \quad \theta_{\frac{l}{2}} = \frac{Ml^2}{12EI}$$

$a \leq x \leq l$

曲げモーメント: $M_x = -\frac{M}{l}x + M$

$$EI \frac{d^2 y_2}{dx^2} = \frac{M}{l}x - M$$

$$EI \frac{dy_2}{dx} = \frac{M}{2l}x^2 - Mx + D_1$$

$$EI y_2 = \frac{M}{6l}x^3 - \frac{M}{2}x^2 + D_1 x + D_2$$

$x=l: y_2=0$

$$\theta_2 = \frac{M}{6EI} \{ 3x^2 - 6lx + (2l^2 + 3a^2) \}$$

$$y_2 = \frac{M}{6EI} \{ x^3 - 3lx^2 + (2l^2 + 3a^2)x - 3la^2 \}$$

$$x=l: \theta_B = \frac{M}{6EI}(-l^2 + 3a^2)$$

$$a = \frac{l}{2}: \theta_B = -\frac{Ml}{24EI} = \theta_A$$

[問題 11.4] x 点の曲げモーメント $M_x = M$

弾性曲線の微分方程式: $\frac{d^2 y}{dx^2} = -\frac{M}{EI}$

これを積分する.

$$\theta = \frac{dy}{dx} = -\frac{M}{EI}(x + C_1), \quad y = -\frac{M}{EI} \left(\frac{1}{2}x^2 + C_1 x + C_2 \right)$$

境界条件 $x=0: y=0, \theta=0$ より $C_1 = C_2 = 0$

したがって $\theta = -\frac{M}{EI}x, \quad y = -\frac{M}{2EI}x^2$

[問題 11.5] 反力は $R_A = -\frac{Pa}{l}$, $R_B = \frac{P(l+a)}{l}$

$$0 \leq x \leq l$$

$$\text{曲げモーメント: } M_x = -\frac{Pa}{l}x$$

$$EI \frac{d^2 y_1}{dx^2} = \frac{Pa}{l}x$$

$$EI \frac{dy_1}{dx} = \frac{Pa}{2l}x^2 + C_1$$

$$EI y_1 = \frac{Pa}{6l}x^3 + C_1 x + C_2$$

$$\text{境界条件: } \begin{aligned} x=0: y_1 &= 0 \\ x=l: y_1 &= 0 \end{aligned}$$

連続条件:

$$x=l: \theta_1 = \theta_2$$

$$\text{この4つの条件より } C_1 = D_1 = -\frac{P a l}{6}, \quad C_2 = D_2 = 0$$

ゆえに

$$\theta_1 = \frac{Pa}{6EI}(3x^2 - l^2)$$

$$y_1 = \frac{Pa}{6EI}(x^3 - l^2 x)$$

$$x=0: \theta_A = -\frac{Pal}{6EI}, \quad x=l: \theta_{1B} = \frac{Pal}{3EI}$$

$$l \leq x \leq l+a$$

$$\text{曲げモーメント: } M_x = -\frac{Pa}{l}x + \frac{P(l+a)}{l}(x-l)$$

$$EI \frac{d^2 y_2}{dx^2} = \frac{Pa}{l}x - \frac{P(l+a)}{l}(x-l)$$

$$EI \frac{dy_2}{dx} = \frac{Pa}{2l}x^2 - \frac{P(l+a)}{2l}(x-l)^2 + D_1$$

$$EI y_2 = \frac{Pa}{6l}x^3 - \frac{P(l+a)}{6l}(x-l)^3 + D_1 x + D_2$$

$$x=l: y_2 = 0$$

$$\theta_2 = \frac{P}{6EI} \{ 3ax^2 - 3(l+a)(x-l)^2 - al^2 \}$$

$$y_2 = \frac{P}{6EI} \{ ax^3 - (l+a)(x-l)^3 - al^2 x \}$$

$$x=l: \theta_{2B} = \frac{Pal}{3EI} = \theta_{1B}$$

$$x=l+a: \theta_C = \frac{Pa}{6EI}(2l+3a), \quad y_C = \frac{Pa^2}{3EI}(l+a)$$

[問題 11.6] (解略) 例題 5.1, 5.5, 問題 5.4 参照. (2)の点 A のたわみ角は負になることに注意.

12. 弾性荷重法によるはりのたわみ

[問題 12.1]

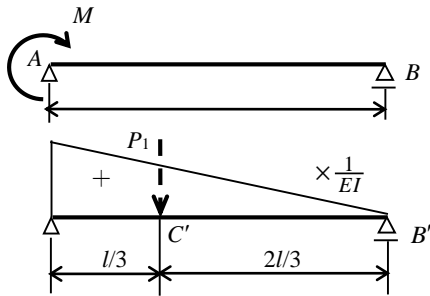


図 21.8

共役ばりにおいて

$$P_1 = \frac{Ml}{2}$$

が三角形の図心位置に作用するとして、反力は

$$R'_A = \frac{Ml}{2} \cdot \frac{2}{3} = \frac{Ml}{3}$$

$$R'_B = \frac{Ml}{2} \cdot \frac{1}{3} = \frac{Ml}{6}$$

ゆえに

$$\theta_A = \frac{Q'_A}{EI} = \frac{Ml}{3EI}$$

$$\theta_B = \frac{Q'_B}{EI} = -\frac{Ml}{6EI}$$

[問題 12.2]

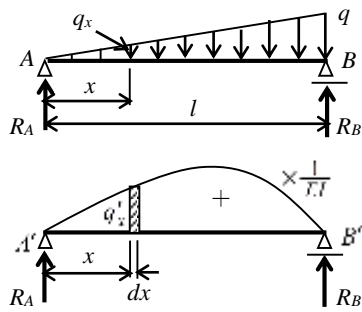


図 21.94

反力は $R_A = \frac{ql}{6}$, $R_B = \frac{ql}{3}$

弾性荷重の荷重強度 q'_x は

$$q'_x = \frac{q}{6l}(l^2x - x^3)$$

弾性荷重の大きさは

$$A = \int_0^l q'_x dx = \frac{q}{6l} \int_0^l (l^2x - x^3) dx$$

$$= \frac{q}{6l} \left[\frac{l^2}{2}x^2 - \frac{1}{4}x^4 \right]_0^l = \frac{ql^3}{24}$$

点 A を通る鉛直軸に対する断面 1 次モーメントは

$$G_x = \int_0^l x dA = \int_0^l x \cdot q'_x dx = \frac{q}{6l} \int_0^l (l^2x^2 - x^4) dx = \frac{q}{6l} \left[\frac{l^2}{3}x^3 - \frac{1}{5}x^5 \right]_0^l = \frac{ql^4}{45}$$

ゆえに、弾性荷重の図心位置は

$$x_0 = \frac{G_x}{A} = \frac{ql^4}{45} \div \frac{ql^3}{24} = \frac{8}{15}l$$

共役ばりの反力は

$$R_{A'} = \frac{1}{l} \cdot \frac{ql^3}{24} \cdot \frac{7}{15}l = \frac{7ql^3}{360}, \quad R_{B'} = \frac{1}{l} \cdot \frac{ql^3}{24} \cdot \frac{8}{15}l = \frac{8ql^3}{360}$$

ゆえに

$$\theta_A = \frac{R_{A'}}{EI} = \frac{7ql^3}{360EI}, \quad \theta_B = \frac{R_{B'}}{EI} = -\frac{8ql^3}{360EI}$$

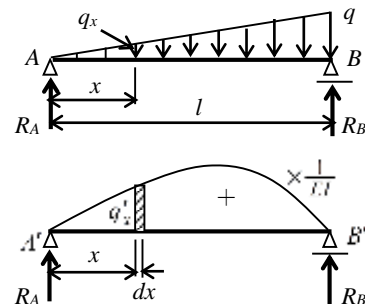


図 21.94

[問題 12.3]

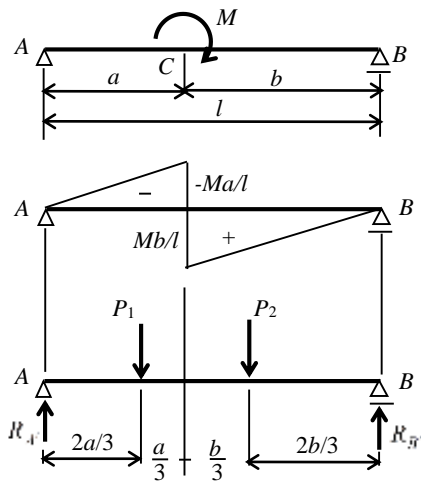


図 21.10

$$R_A = -\frac{M}{l}, \quad R_B = \frac{M}{l}$$

$$P_1 = -\frac{Ma^2}{2l}, \quad P_2 = \frac{Mb^2}{2l}$$

$$R_{A'} = \frac{M}{6l^2}(-a^3 - 3a^2b + 2b^3),$$

$$R_{B'} = \frac{M}{6l^2}(-2a^3 + 3ab^2 + b^3)$$

$$Q_{C'} = R_{A'} - P_1 = \frac{M}{3l^2}(a^3 + b^3)$$

$$M_{C'} = R_{A'}a - P_1 \frac{a}{3} = \frac{Mab}{3l^2}(-a^2 + b^2)$$

以上より

$$\theta_{A'} = \frac{Q_{A'}}{EI} = \frac{M}{6EI^2}(-a^3 - 3a^2b + 2b^3), \quad \theta_B = \frac{Q_{B'}}{EI} = -\frac{M}{6EI^2}(-2a^3 + 3ab^2 + b^3)$$

$$\theta_{C'} = \frac{Q_{C'}}{EI} = \frac{M}{3EI^2}(a^3 + b^3), \quad y_C = \frac{M_{C'}}{EI} = \frac{Mab}{3EI^2}(-a^2 + b^2)$$

[問題 12.4]

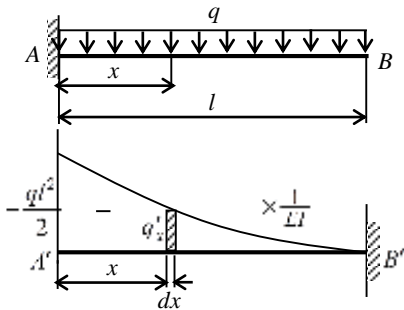


図 21.11

x 点の曲げモーメントは

$$q'_x = -\frac{q}{2}(x-l)^2$$

点 A から x の点の微小面積について考える.

$$R_{B'} = \int_0^l q'_x dx = -\frac{q}{2} \int_0^l (x-l)^2 dx = -\frac{ql^3}{6}$$

$$Q_{B'} = -R_{B'} = \frac{ql^3}{6}, \quad \therefore \theta_B = \frac{Q_{B'}}{EI} = \frac{ql^3}{6EI}$$

$$M_{B'} = \int_0^l (q'_x dx)(l-x) = \frac{q}{2} \int_0^l (x-l)^3 dx = \frac{ql^4}{8}$$

$$\therefore y_B = \frac{M_{B'}}{EI} = \frac{ql^4}{8EI}$$

[問題 12.5]

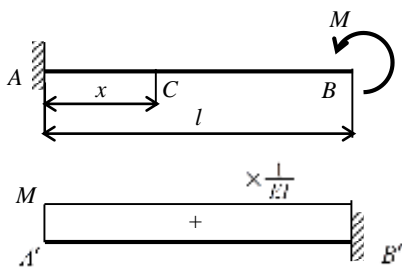


図 21.12

曲げモーメントは正で一定である.

$$R_{B'} = Ml, \quad \theta_B = \frac{Q_{B'}}{EI} = -\frac{Ml}{EI}$$

$$M_{B'} = -Ml \cdot \frac{l}{2}, \quad y_B = \frac{M_{B'}}{EI} = -\frac{Ml^2}{2EI}$$

[問題 12.6]

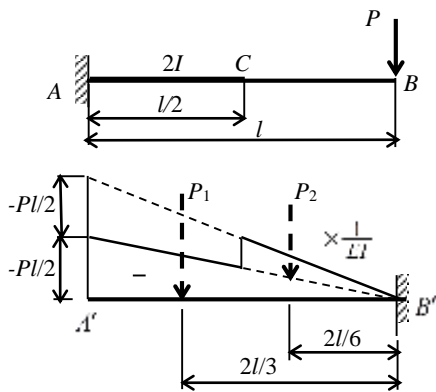


図 21.13

弾性荷重を $1/EI$ で統一するために、断面 2 次モーメントが $2I$ の部分の曲げモーメントを $1/2$ 倍する。

$$P_1 = -\frac{Pl^2}{4}, \quad P_2 = -\frac{Pl^2}{16}$$

$$R_{B'} = P_1 + P_2 = -\frac{5Pl^2}{16}, \quad \therefore \theta_B = \frac{Q_{B'}}{EI} = \frac{5Pl^2}{16EI}$$

$$M_{B'} = -P_1 \frac{2l}{3} - P_2 \frac{l}{3} = \frac{3Pl^3}{16}, \quad \therefore y_B = \frac{M_{B'}}{EI} = \frac{3Pl^3}{16EI}$$

[問題 12.7]

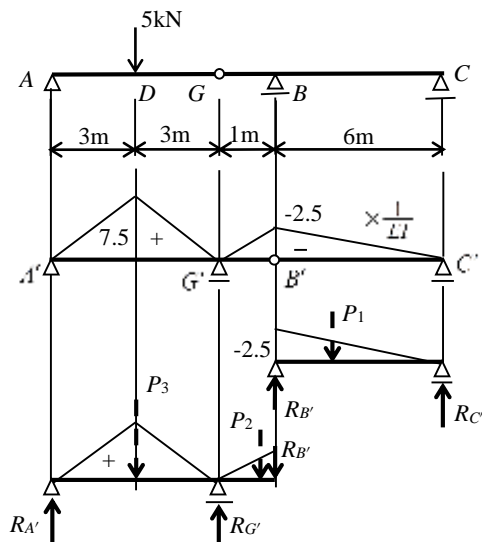


図 21.14

単位は[kN], [kNm]とする。

$$P_1 = -7.5, \quad P_2 = -1.25, \quad P_3 = 22.5$$

$$R_{B'} = -5, \quad R_{C'} = -2.5$$

$$\therefore \theta_B = -\frac{5}{EI}, \quad \theta_C = \frac{2.5}{EI}$$

$$\sum M_{G'} = 0: R_{A'} \cdot 6 - 22.5 \cdot 3 + (-1.25) \cdot \frac{2}{3} + R_{B'} \cdot 1 = 0$$

$$\therefore R_{A'} = 12.22, \quad \therefore \theta_A = \frac{Q_{A'}}{EI} = \frac{12.22}{EI}$$

$$M_{G'} = -P_2 \cdot \frac{2}{3} - R_{B'} \cdot 1 = 1.25 \cdot \frac{2}{3} + 5 = \frac{2.5}{3} = 5.83$$

$$\therefore y_G = \frac{M_{G'}}{EI} = \frac{5.83}{EI}$$

$${}_r Q_{G'} = P_2 + R_{B'} = -6.25, \quad {}_l Q_{G'} = R_{A'} - P_3 = -10.28$$

$$\therefore {}_r \theta_G = -\frac{6.25}{EI}, \quad {}_l \theta_G = -\frac{10.28}{EI}$$

18 静定トラス

[問題 18.1]

$$(1) \quad \cos \theta = \frac{4}{5}, \quad \sin \theta = \frac{3}{5},$$

$$N_{AC} \sin \theta + P = 0, \quad \therefore N_{AC} = -\frac{5}{3}P, \quad N_{AC} \cos \theta + N_{AB} = 0, \quad \therefore N_{AB} = -N_{AC} \cos \theta = \frac{4}{3}P$$

$$(2) \quad \cos \theta = \sin \theta = \frac{1}{\sqrt{2}}$$

$$N_{CB} = 0, \quad N_{CD} = -P, \quad N_{BD} \sin \theta + N_{CD} = 0, \quad \therefore N_{BD} = \sqrt{2}P$$

$$N_{BD} \cos \theta + N_{AD} = 0, \quad \therefore N_{AD} = -N_{BD} \cos \theta = -P$$

$$(3) \quad \sum M_A = 0: -H_D a + Pa = 0, \quad \therefore H_D = P, \quad \sum M_D = 0: V_A a - H_A a = 0, \quad \therefore V_A = H_A = P$$

$$N_{BD} = 0, \quad N_{CD} = -P, \quad N_{AC} = -P, \quad N_{AB} = -P$$

$$N_{CB} \cos \theta + N_{CD} = 0, \quad \therefore N_{CB} = -\frac{N_{CD}}{\cos \theta} = \sqrt{2}P$$

$$(4) \quad \sum M_B = 0: R_A a + P \cdot 2a = 0, \quad \therefore R_A = -2P, \quad R_B = 2P, \quad H_A = -P$$

$$N_{DE} \sin \theta + P = 0, \quad \therefore N_{DE} = -\frac{P}{\sin \theta} = -\sqrt{2}P, \quad N_{DE} \cos \theta + N_{CE} = 0, \quad \therefore N_{CE} = -N_{DE} \cos \theta = P$$

$$N_{CD} = 0, \quad N_{AC} = N_{CE} = P, \quad N_{AB} = 0, \quad N_{BD} = -2P$$

$$H_A + N_{AD} \cos \theta = 0, \quad \therefore N_{AD} = -\frac{H_A}{\cos \theta} = \sqrt{2}P$$

$$(5) \quad \sin \theta = \frac{4}{5}, \quad \cos \theta = \frac{3}{5}$$

反力

$$\sum M_B = 0: R_A \cdot 12 - 2 \cdot 9 - 4 \cdot 6 - 5 \cdot 3 = 0, \quad \therefore R_A = \frac{57}{12} = 4.75 \text{ kN}, \quad R_B = 2 + 4 + 5 - \frac{57}{12} = \frac{75}{12} = 6.25 \text{ kN}$$

部材力

$$A: D_1 \sin \theta + R_A = 0, \quad \therefore D_1 = -5.94 \text{ kN}, \quad D_1 \cos \theta + L_1 = 0, \quad \therefore L_1 = 3.56 \text{ kN}$$

$$1: D_1 \sin \theta + D_2 \sin \theta + 2 = 0, \quad \therefore D_2 = 3.44 \text{ kN}, \quad -D_1 \cos \theta + D_2 \sin \theta + U_1 = 0, \quad \therefore U_1 = -5.63 \text{ kN}$$

$$2: D_2 \sin \theta + D_3 \sin \theta - 4 = 0, \quad \therefore D_3 = 1.56 \text{ kN}$$

$$B: D_4 \sin \theta + R_B = 0, \quad \therefore D_4 = -7.81 \text{ kN}, \quad D_4 \cos \theta + L_2 = 0, \quad \therefore L_2 = 4.69 \text{ kN}$$

$$(6) \quad \sin \theta = \frac{4}{5}, \quad \cos \theta = \frac{3}{5}$$

反力

$$\sum M_B = 0: R_A \cdot 9 - 10 \cdot 6 - 5 \cdot 3 = 0, \quad \therefore R_A = \frac{25}{3} = 8.33 \text{ kN}, \quad R_B = 10 + 5 + \frac{25}{3} = \frac{20}{3} = 6.67 \text{ kN}$$

部材力

$$A: D_1 \sin \theta + R_A = 0, \quad \therefore D_1 = -10.41 \text{ kN}, \quad D_1 \cos \theta + L_1 = 0, \quad \therefore L_1 = 6.25 \text{ kN}$$

$$1': D_1 \sin \theta + V_1 = 0, \quad \therefore V_1 = 8.33 \text{ kN}, \quad -D_1 \cos \theta + U_1 = 0, \quad \therefore U_1 = -6.25 \text{ kN}$$

$$2: R_A + D_2 \sin \theta - 10, \quad \therefore D_2 = 2.09 \text{ kN}$$

$$B: D_3 \sin \theta + R_B = 0, \quad \therefore D_3 = -8.33 \text{ kN}, \quad D_3 \cos \theta + L_3 = 0, \quad \therefore L_3 = 5.00 \text{ kN}$$

$$2: V_2 = 0, \quad L_2 = L_3 = 5.00 \text{ kN}$$

[問題 18.2]

$$(1) \cos \theta = \sin \theta = \frac{1}{\sqrt{2}}$$

$$\sum M_B = 0: R_A \cdot 4a - P \cdot 3a - 2P \cdot 2a - 4P \cdot a = 0, \quad \therefore R_A = \frac{11P}{4} = 2.75P, \quad R_B = \frac{17}{4}P$$

$$U_2 = -\frac{M'_2}{a} = -\frac{R_A \cdot 2a - Pa}{a} = -\frac{18}{4}P = -4.5P, \quad D_2 = \frac{Q_{1-2}}{\sin \theta} = \frac{R_A - P}{\sin \theta} = \frac{7\sqrt{2}}{4}P = 2.47P,$$

$$L_1 = \frac{M_1}{a} = \frac{11}{4}P = 2.75P, \quad V_1 = -Q_{A-1} = -R_A + P = -\frac{7}{4}P = -1.75P$$

$$(2) \sin \theta = \frac{4}{5}, \quad \cos \theta = \frac{3}{5}$$

$$\sum M_B = 0: R_A \cdot 6 - 10 \cdot 4 = 0, \quad \therefore R_A = \frac{40}{6} = 6.67\text{kN}, \quad R_B = -\frac{40}{6} = -6.67\text{kN}, \quad H_A = 10\text{kN}$$

$$U_2 = -10\text{kN}, \quad V_2 = 0, \quad D_2 \sin \theta + V_2 + R_B = 0, \quad \therefore D_2 = -\frac{R_B}{\sin \theta} = \frac{25}{3} = 8.33\text{kN},$$

$$D_2 \cos \theta + L_1 = 0, \quad \therefore L_1 = -D_2 \cos \theta = -5.00\text{kN}$$

(3)

$$\sum M_B = 0: R_A \cdot 12 - 4 \cdot 12 - 10 \cdot 9 - 4 \cdot 3 = 0, \quad \therefore R_A = \frac{150}{12} = 12.5\text{kN}, \quad R_B = 4 + 10 + 4 - 12.5 = 5.5\text{kN}$$

$$U_2 = -\frac{M_2}{h} = -\frac{(R_A - 4) \cdot 6 + 10 \cdot 3}{4} = -\frac{42}{8} = -5.25\text{kN}, \quad D_2 = \frac{Q_{1-2}}{\sin \theta} = -\frac{15}{8} = -1.875\text{kN},$$

$$L_2 = \frac{M'_1}{h} = \frac{(R_A - 4) \cdot 3}{4} = \frac{51}{8} = 6.375\text{kN}, \quad V_2 = -Q_{1-2} = -(R_A - 4) = -\frac{17}{2} = -8.5\text{kN}$$

$$(4) \sin \theta = \cos \theta = \frac{1}{\sqrt{2}}$$

$$R_A = R_B = 15\text{kN}$$

$$A: U_1 \sin \theta + R_A = 0, \quad \therefore U_1 = -15\sqrt{2} = -21.15\text{kN}$$

$$U_1 \cos \theta + L_1 = 0, \quad \therefore L_1 = -U_1 \cos \theta = 15\text{kN}$$

$$D: D_1 = -5\sqrt{2} = -7.07\text{kN}, \quad -U_1 - 5\sqrt{2} + U_2 = 0, \quad \therefore U_2 = U_1 + 5\sqrt{2} = -10\sqrt{2} = -14.14\text{kN}$$

$$F: U_2 \sin \theta + U'_2 \sin \theta + V_1 + 10 = 0, \quad \therefore V_1 = 10\text{kN}$$

(5) 三角形の相似より

$$R_A = R_B = \frac{3}{2}P$$

$$\Delta 1'2'M \sim \Delta 22'N \text{ より } 1'2':1'M = 2'2':2N, \quad \therefore 2N = h = \frac{1'M \times 2'2'}{1'2'} = \frac{4 \times 5}{\sqrt{4^2 + 1^2}} = \frac{20}{\sqrt{17}} = 4.85\text{m}$$

$$\Delta 1'O1 \sim \Delta 2'1'M \text{ より } x:4 = 4:1, \quad \therefore x = \frac{16}{1} = 16\text{m}, \quad \therefore a = 12\text{m}$$

$$\Delta 2OP \sim \Delta 21'1 \text{ より } OP:O2 = 1'1':1'2', \quad \therefore OP = b = \frac{20 \times 4}{4\sqrt{2}} = \frac{20}{\sqrt{2}} = 10\sqrt{2} = 14.14\text{m}$$

$$\sum M_2 = 0: R_A \cdot 2\lambda - P \cdot \lambda + U_2 \cdot h = 0, \quad \therefore U_2 = -\frac{R_A \cdot 2\lambda - P \cdot \lambda}{h} = -\frac{8P}{4.85} = -1.65P$$

$$\sum M'_1 = 0: R_A \cdot \lambda - L_2 \cdot h_1 = 0, \quad \therefore L_2 = -\frac{R_A \cdot \lambda}{h_1} = 1.5P$$

$$\sum M_O = 0: -R_A \cdot a + P(a + \lambda) + D_2 \cdot b = 0, \quad \therefore D_2 = \frac{R_A \cdot a - P(a + \lambda)}{b} = \frac{\sqrt{2}P}{10} = 0.14P$$

(6)

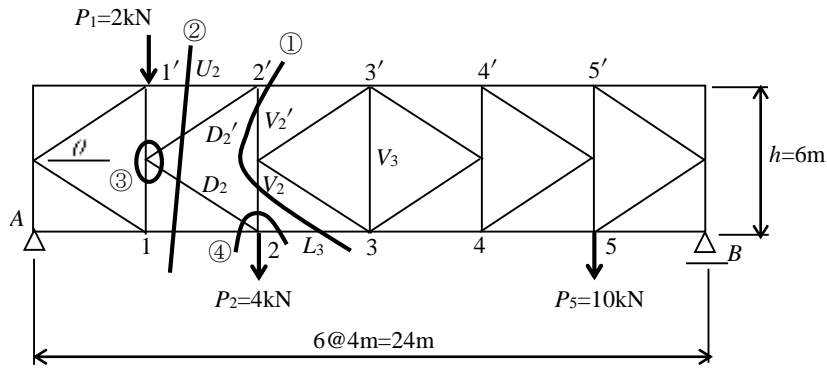


図 8.19

$$R_A \cdot 24 - 2 \times 20 - 4 \times 16 - 10 \times 4 = 0, \quad \therefore R_A = 6\text{kN}, \quad R_B = 2 + 4 + 10 - 6 = 10\text{kN}$$

$$\textcircled{1} : \quad \sum M_{2'} = 0 : R_A \cdot 8 - 2 \cdot 4 - L_3 \cdot 6 = 0, \quad L_3 = \frac{20}{3} = 6.67\text{kN}$$

$$\textcircled{3} : \quad D_2 = -D_2'$$

$$\textcircled{2} : \quad \sum V = 0 : R_A - 2 + (D_2' - D_2) \sin \theta = 0, \quad \therefore D_2' = -\frac{R_A - 2}{2 \sin \theta} = -\frac{10}{3} = -3.33\text{kN}$$

$$\sum M_1 = 0 : R_A \cdot 4 - U_2 \cdot 6 = 0, \quad U_2 = -4\text{kN}$$

$$\textcircled{4} : \quad \sum V = 0 : D_2 \sin \theta + V_2 - 4 = 0, \quad \therefore V_2 = 4 - D_2 \sin \theta = 2\text{kN}$$

$$\sum V = 0 : D_2' \sin \theta + V_2' = 0, \quad \therefore V_2' = -D_2' \sin \theta = 2\text{kN}$$

$$V_3 = 0$$

(7)

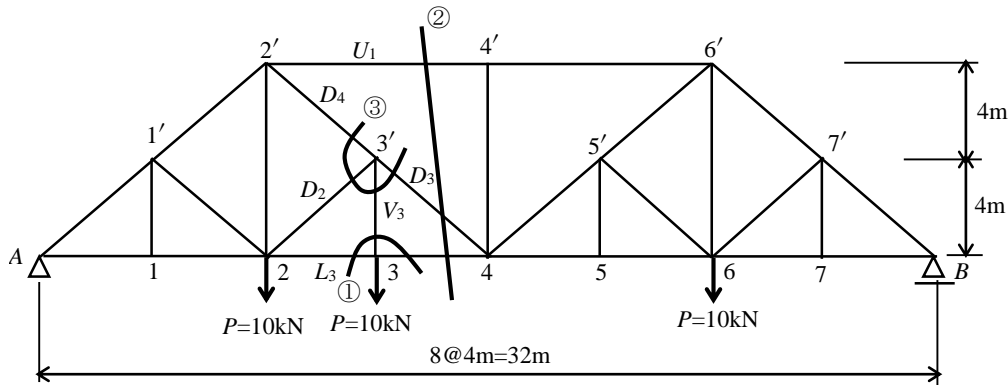


図 8.20

$$R_A \cdot 32 - 10 \times 24 - 10 \times 20 - 10 \times 8 = 0, \quad \therefore R_A = \frac{65}{4} = 16.25\text{kN}, \quad R_B = 13.75\text{kN}$$

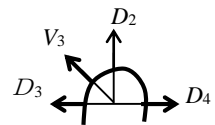
$$\textcircled{1} : \quad V_3 = 10\text{kN}$$

$$\textcircled{2} : \quad \sum M_4 = 0 : R_A \cdot 16 - 10 \times 8 - 10 \times 4 + U_1 \times 8 = 0, \quad \therefore U_1 = -\frac{35}{2} = -17.5\text{kN}$$

$$\sum V = 0 : R_A - 10 - 10 - D_3 \sin \theta = 0, \quad \therefore D_3 = -\frac{15\sqrt{2}}{4} = -3.75\sqrt{2} = -5.29\text{kN}$$

$$\textcircled{3} : \quad \sum V = 0 : V_3 \sin \theta + D_2 = 0, \quad \therefore D_2 = -5\sqrt{2} = -7.07\text{kN}$$

$$\sum H = 0 : D_3 + V_3 \cos \theta - D_4 = 0, \quad \therefore D_4 = \frac{5\sqrt{2}}{4} = 1.25\sqrt{2} = 1.77\text{kN}$$

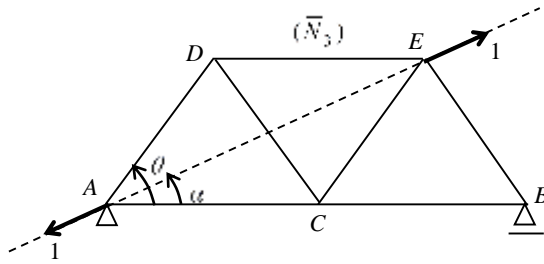


$$\textcircled{2}' : \quad \sum M_{2'} = 0 : R_A \cdot 8 + 10 \cdot 4 - L_4 \cdot 8 = 0, \quad \therefore L_4 = \frac{1}{8}(R_A \cdot 8 + 10 \cdot 4) = 21.25\text{kN} = L_3$$

[問題 18.3] 図(1),(2),(3)の部材力 (N, \bar{N}_1, \bar{N}_2) を下表に記す.

部材	l	N	\bar{N}_1	\bar{N}_2
1	6	6.00	0.375	1
2	6	9.75	0.375	0
3	5	-10.0	-0.625	0
4	5	7.50	0.625	0
5	5	1.25	0.625	0
6	5	-16.25	-0.625	0
7	6	-10.50	-0.750	0

(4)



$$R_A = R_B = 0, \quad \sin \theta = 4/5 = 0.8, \quad \cos \theta = 3/5 = 0.6, \quad \sin \alpha = 4/\sqrt{97} = 0.406, \quad \cos \alpha = 9/\sqrt{97} = 0.914$$

1) 節点 A : $R_A + N_3 \sin \theta - 1 \cdot \sin \alpha = 0, \quad \therefore N_3 = \frac{\sin \alpha}{\sin \theta} = \frac{5}{\sqrt{97}} = 0.508$

$$N_1 + N_3 \cos \theta - \cos \alpha = 0, \quad \therefore N_1 = \cos \alpha - N_3 \cos \theta = \frac{6}{\sqrt{97}} = 0.609$$

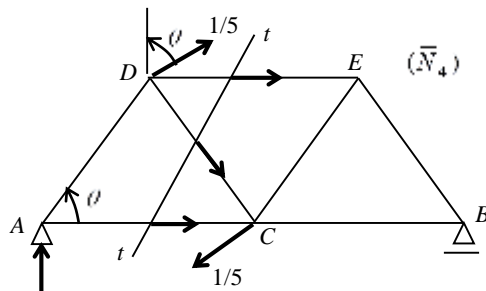
2) 節点 B : $N_3 \sin \theta + N_4 \sin \alpha = 0, \quad \therefore N_4 = -N_3 = -\frac{5}{\sqrt{97}} = -0.508$

$$N_7 + N_4 \cos \theta - N_3 \cos \theta = 0, \quad \therefore N_7 = (N_3 - N_4) \cos \theta = \frac{6}{\sqrt{97}} = 0.609$$

3) 節点 C : $N_4 \sin \theta + N_5 \sin \theta = 0, \quad \therefore N_5 = -N_4 = \frac{5}{\sqrt{97}} = 0.508$

$$N_6 = 0, \quad N_2 = 0$$

(5)



$$R_A = -R_B = -1/12 = -0.083, \quad \sin \theta = 4/5 = 0.8, \quad \cos \theta = 3/5 = 0.6$$

1) 節点 A : $R_A + N_3 \sin \theta = 0, \quad \therefore N_3 = -\frac{R_A}{\sin \theta} = \frac{5}{48} = 0.104$

$$N_1 + N_3 \cos \theta = 0, \quad \therefore N_1 = -N_3 \cos \theta = -\frac{3}{48} = -0.0625$$

2) 断面 t-t $\sum M_C = 0: 6R_A + 5 \cdot \frac{1}{5} + 4N_7 = 0, \quad \therefore N_7 = -\frac{1}{8} = -0.125$

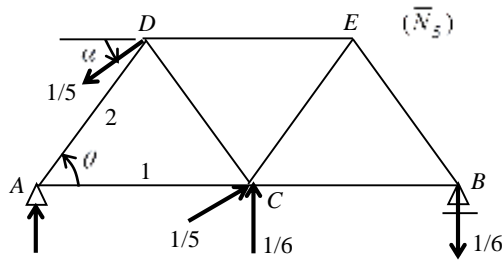
$$\sum V = 0: R_A + \frac{1}{5} \cos \theta - N_4 \sin \theta = 0, \quad \therefore N_4 = \frac{11}{240} = 0.0458$$

3) 節点 B: $R_B + N_6 \sin \theta = 0, \quad \therefore N_6 = -\frac{R_B}{\sin \theta} = -\frac{5}{48} = -0.104$

$$N_2 + N_6 \cos \theta = 0, \quad \therefore N_2 = -N_6 \cos \theta = -\frac{3}{48} = -0.0625$$

4) 節点 E: $N_5 \sin \theta + N_6 \sin \theta = 0, \quad \therefore N_5 = -N_6 = \frac{5}{48} = 0.104$

(6)



$$R_A = R_B = 0, \quad \sin \theta = 4/5 = 0.8, \quad \cos \theta = 3/5 = 0.6$$

$$\cos \alpha = \cos(90 - \theta) = \sin \theta = 4/5, \quad \sin \alpha = \sin(90 - \theta) = \cos \theta = 3/5$$

1) $N_1 = N_2 = 0$

2) 節点 B: $-\frac{1}{6} + N_6 \sin \theta = 0, \quad \therefore N_6 = \frac{1/6}{\sin \theta} = \frac{5}{24} = 0.208$

$$N_2 + N_6 \cos \theta = 0, \quad \therefore N_2 = -N_6 \cos \theta = -\frac{1}{8} = -0.125$$

3) 節点 E: $N_5 \sin \theta + N_6 \sin \theta = 0, \quad \therefore N_5 = -N_6 = -\frac{5}{48} = -0.104$

$$N_7 + N_5 \cos \theta - N_6 \cos \theta = 0, \quad \therefore N_7 = (N_6 - N_5) \cos \theta = \frac{1}{4} = 0.250$$

4) 節点 C: $N_4 \sin \theta + N_5 \sin \theta + \frac{1}{5} \sin \alpha + \frac{1}{6} = 0, \quad \therefore N_4 = -\frac{5}{4} \left(N_5 \frac{4}{5} + \frac{1}{5} \cdot \frac{3}{5} + \frac{1}{6} \right) = -\frac{3}{20} = -0.150$

以上をまとめる.

部材	l	\bar{N}_3	\bar{N}_4	\bar{N}_5
1	6	0.609	-0.063	0.0
2	6	0.0	0.063	-0.125
3	5	0.508	0.104	0.0
4	5	-0.508	0.046	-0.150
5	5	0.508	0.104	-0.208
6	5	0.0	-0.104	0.208
7	6	0.609	-0.125	0.250

20. トラスの影響線

[問題 20.1]

(1) ハウトラスの影響線.

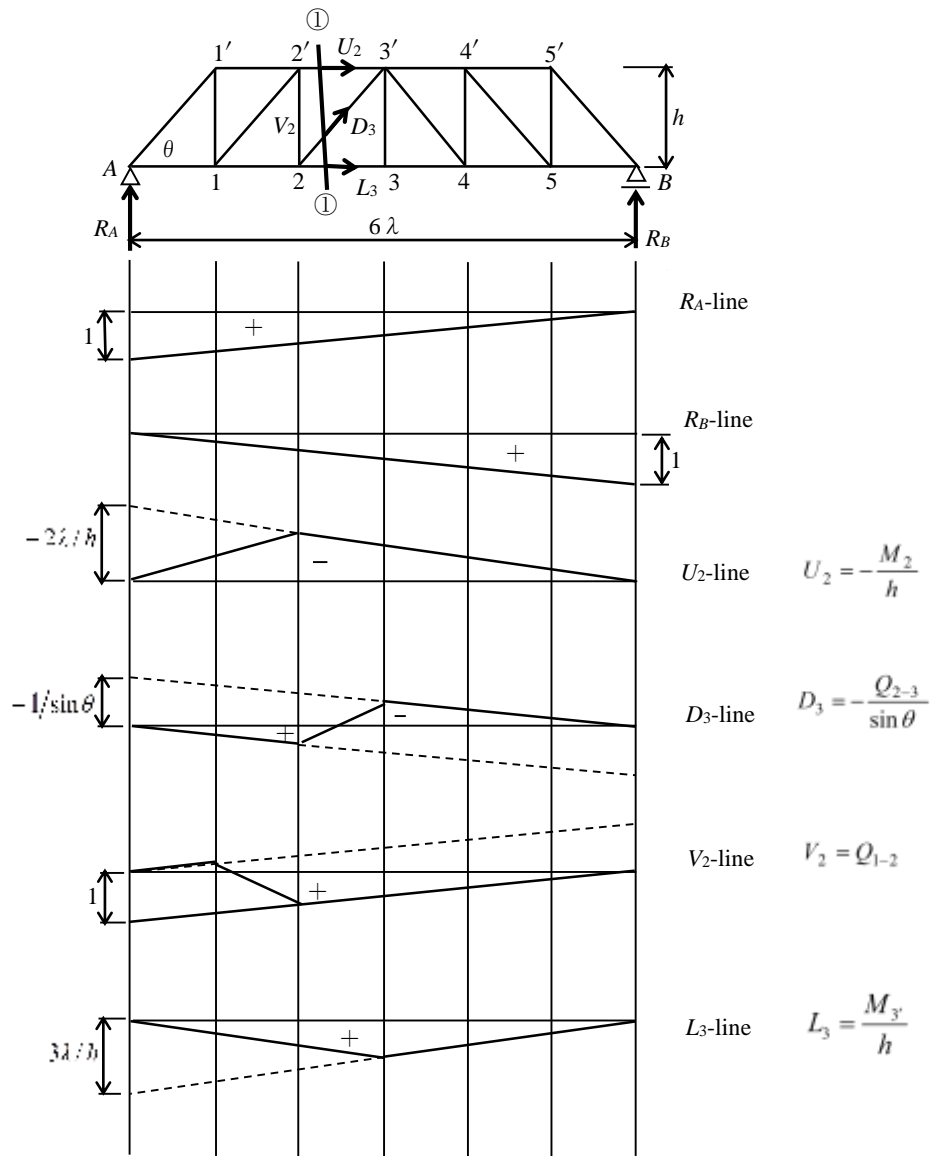


図 8.24

(2) プラットトラスの影響線.

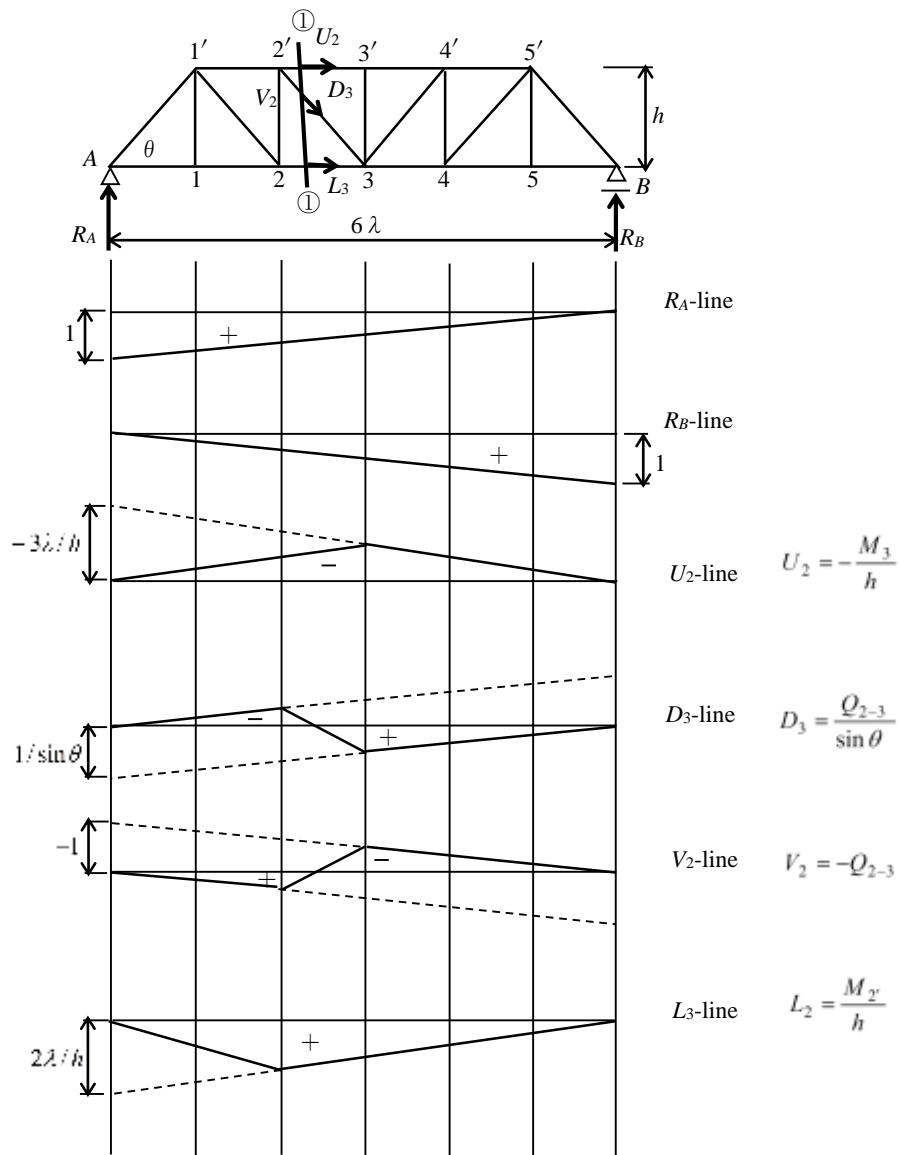


図 8.25

(3) ワーレントラスの影響線.

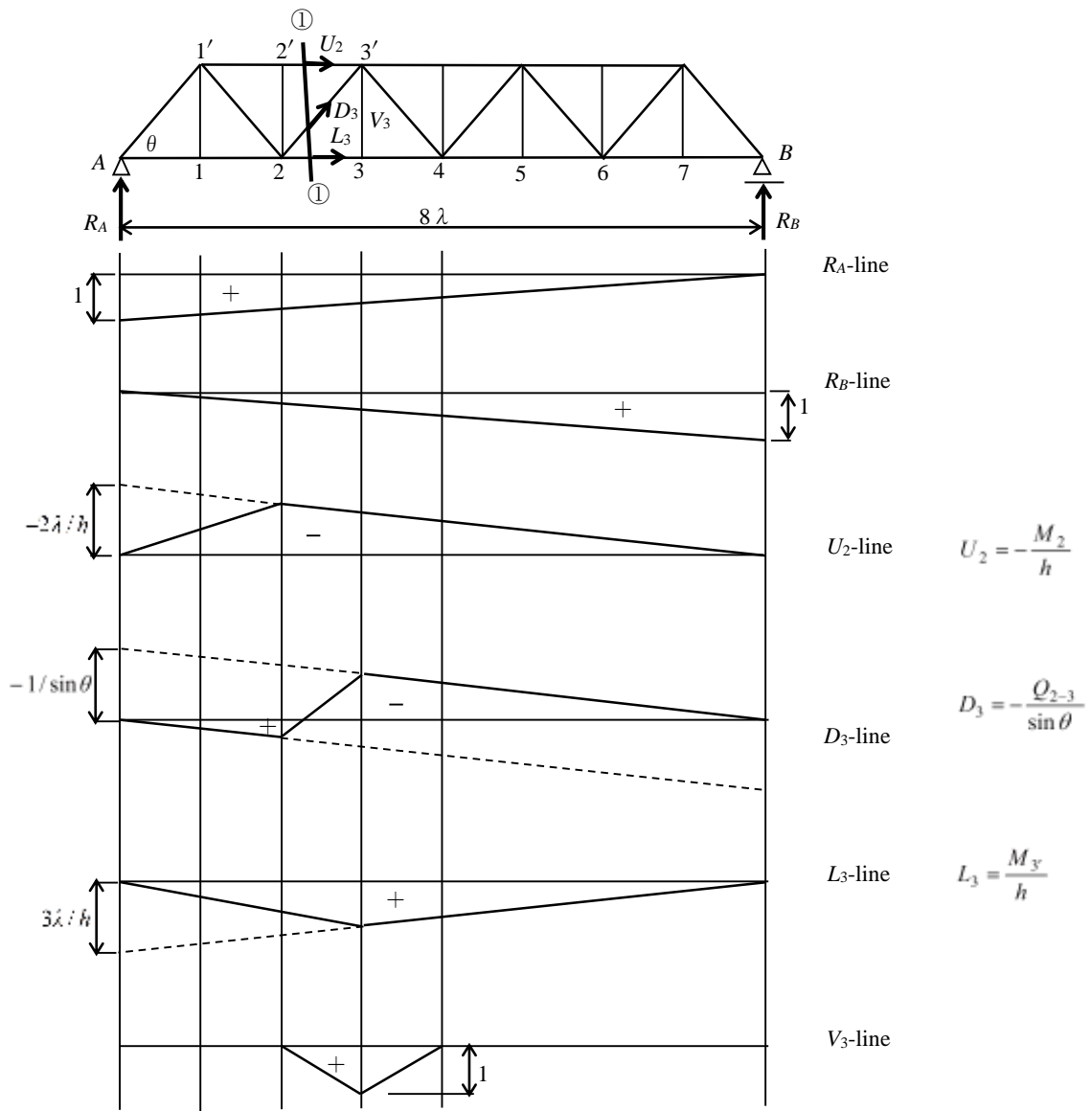


図 8.26

(4) 曲弦トラスの影響線.

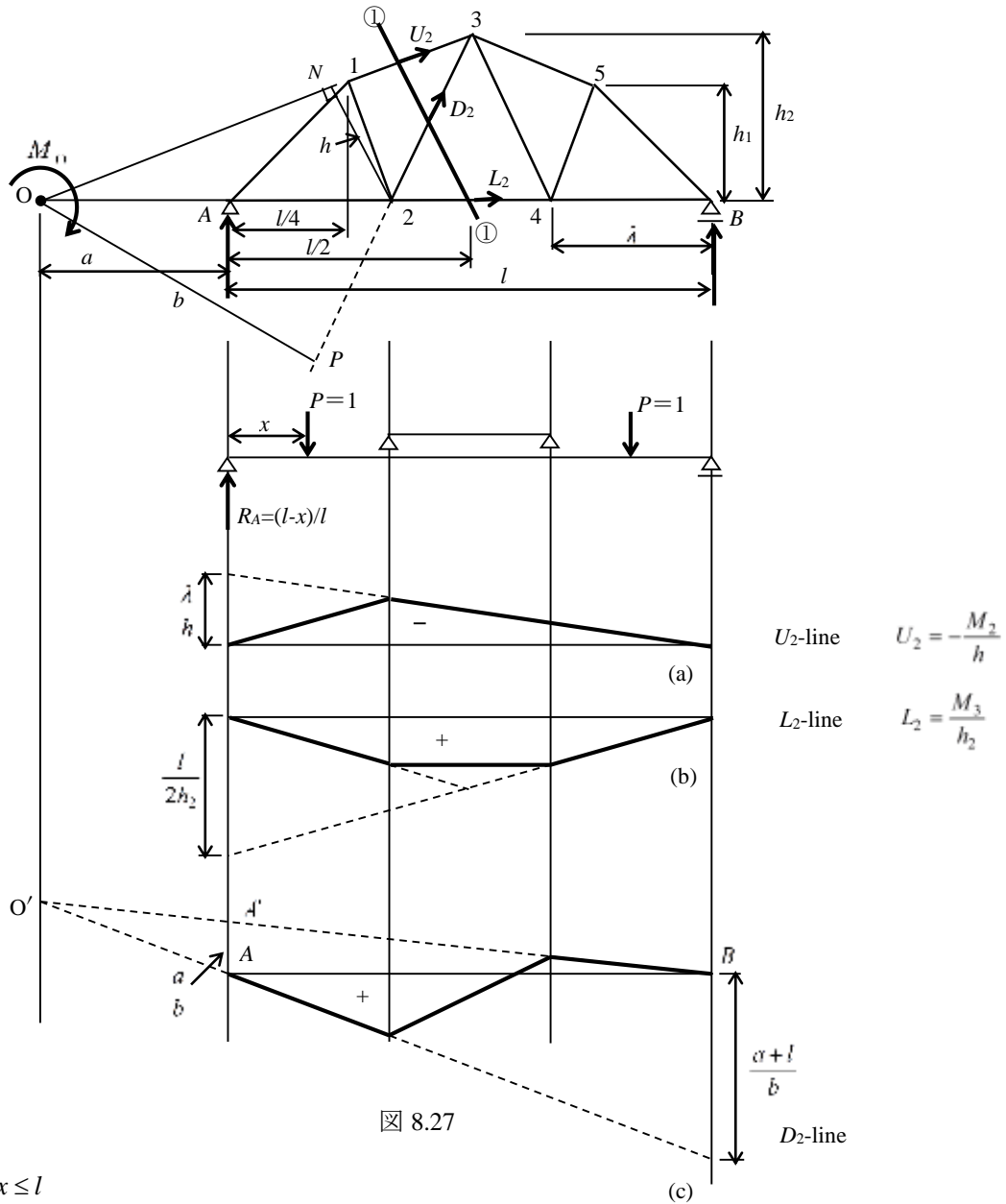


図 8.27

D_2 -line

$$2\lambda \leq x \leq l$$

$$\sum M_O = 0$$

$$-R_A a - D_2 b = 0, \quad \therefore D_2 = -\frac{a}{b} R_A = -\frac{a}{b} \frac{l-x}{l}$$

$$x=0: D_2 = -\frac{a}{b}, \quad x=l: D_2 = 0$$

$$0 \leq x \leq \lambda$$

$$\sum M_{O'} = 0$$

$$-R_A a + 1 \cdot (a+x) - D_2 b = 0, \quad \therefore D_2 = \frac{1}{b} [-R_A a + 1 \cdot (a+x)] = -\frac{1}{b} \left[\frac{l-x}{l} a - (a+x) \right]$$

$$x=0: D_2 = 0, \quad x=l: D_2 = \frac{l+a}{b}$$

これを描くには、図 8.27(c)において、点 B と点 A で $-a/b$ の大きさの点 A' をとり、BA' を O' まで延長する。そして O' から点 A に引いた線を延長して、区間 2-4 で修正する

(5) 曲弦トラスの影響線.

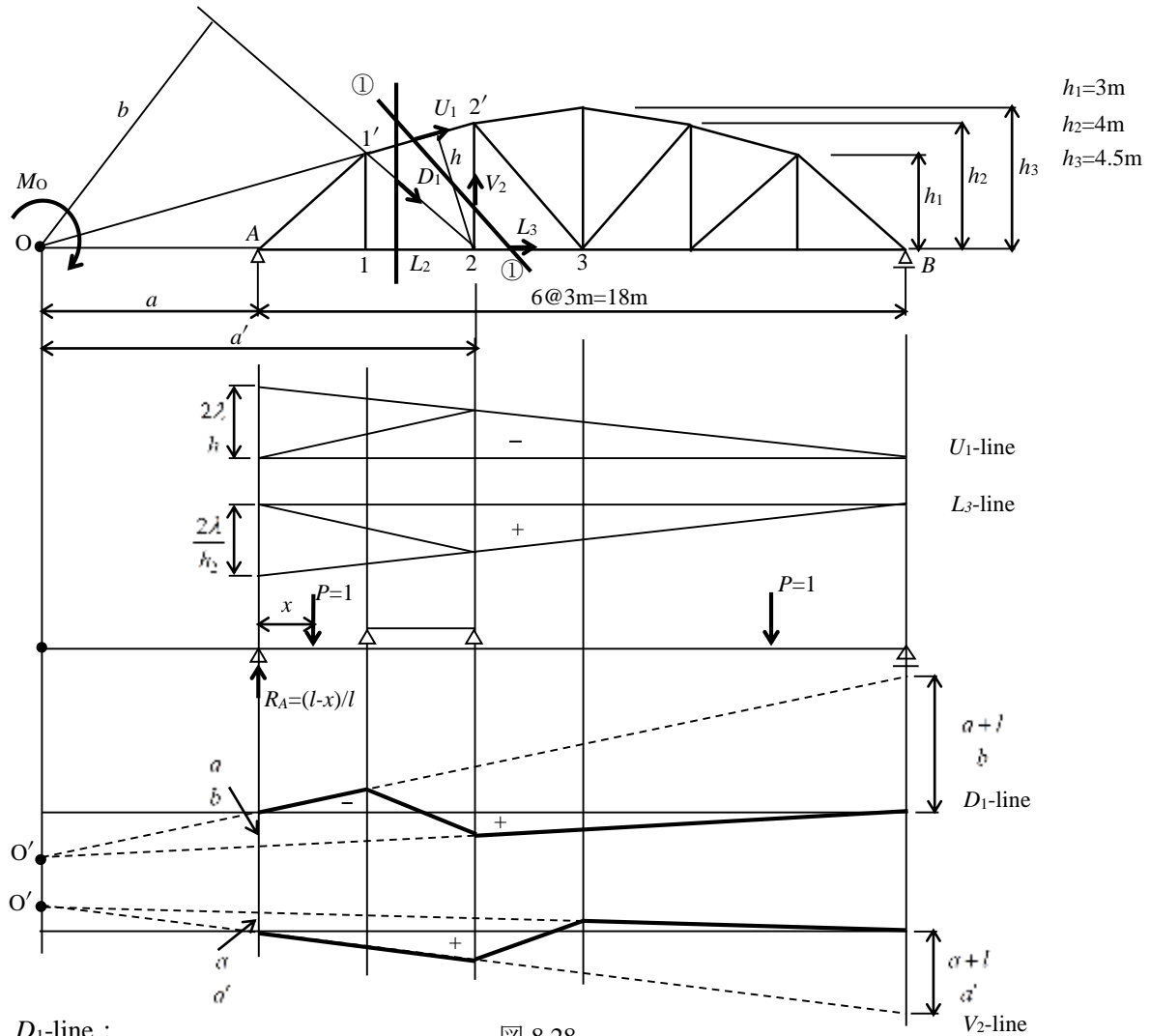


図 8.28

D₁-line :

$$0 \leq x \leq \lambda$$

$$\sum M_O = 0: -R_A a + 1 \cdot (a + x) + D_1 b = 0, \therefore D_1 = -\frac{1}{b} \left(1 + \frac{a}{l} \right) x, \quad x=0: D_1 = 0, \quad x=l: D_1 = -\frac{l+a}{b}$$

$$2\lambda \leq x \leq l$$

$$\sum M_O = 0: -R_A a + D_1 b = 0, \therefore D_1 = R_A a = \frac{a}{b} \left(\frac{l-x}{l} \right), \quad x=0: D_1 = \frac{a}{b}, \quad x=l: D_1 = 0$$

V₂-line :

$$0 \leq x \leq 2\lambda$$

$$\sum M_O = 0: -R_A a + 1 \cdot (a + x) - V_2 a' = 0, \therefore V_2 = \frac{1}{a'} \left(1 + \frac{a}{l} \right) x, \quad x=0: V_2 = 0, \quad x=l: V_2 = \frac{l+a}{a'}$$

$$3\lambda \leq x \leq l$$

$$\sum M_O = 0: -R_A a - V_2 a' = 0, \therefore V_2 = -\frac{a}{a'} \left(\frac{l-x}{l} \right), \quad x=0: V_2 = -\frac{a}{a'}, \quad x=l: V_2 = 0$$

V-line を描くには、点 A 上で $-a/b$ の大きさをとり、点 B で 0 の線分を、O' まで延長する。そして O' から点 A に引いた線を延長して、区間 2-4 で修正する。

(6) Kトラスの影響線.

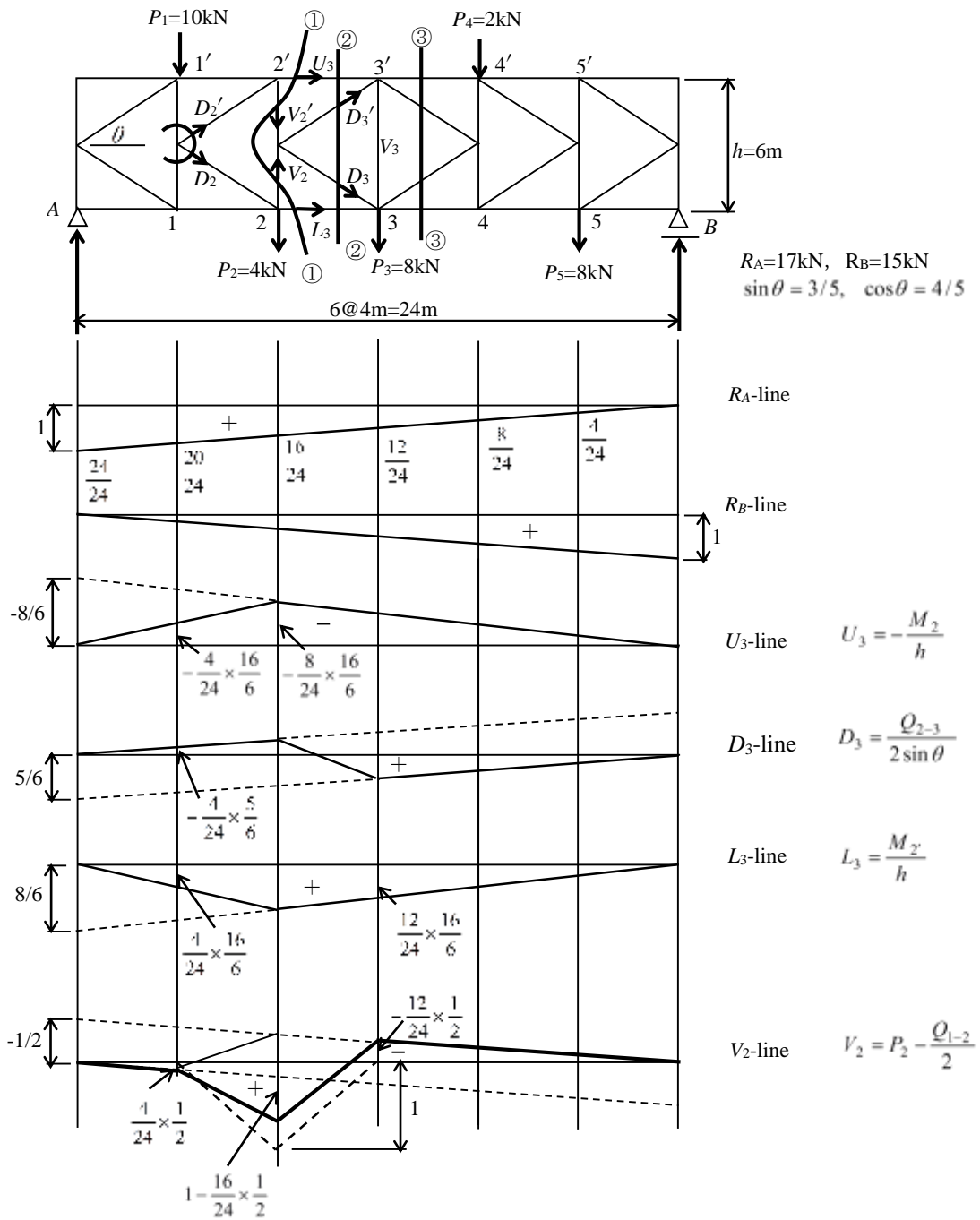


図 8.29