

## SM12I. FOR

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12元行列式の応力公式の係数, 応力を求め,  
H2. FOR より特異解を求める  
NGRAPH で出力できるように分類する.

&lt;941111&gt;&lt;951018&gt;&lt;951119&gt;

Program by H. HAMANO

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IMPLICIT DOUBLE PRECISION(A-H, O-Z)
REAL*8 PSI1, PSI2, G1, G2, G3, C1, C2, FAI, RRL, RIL, PO, PI,
1      FAII (500), RRE (500), RIM (500)
COMPLEX*16 A33
CHARACTER*15 NAME, NAM, NA
WRITE (6, '(A¥)') ' INPUT FILE NAME ( Ex. P605. DAT ) =?'
READ (5, 50) NAME
*   WRITE (6, '(A¥)') ' OUTPUT FILE NAME ( Ex. GO. DAT  ) =?'
*   READ (5, 50) NA
50  FORMAT (A)
   NA=' GO. DAT'
   WRITE (6, '(A¥)') ' 領域角  =?'
   READ (5, *) KAKU

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読み込み用ファイルオープン

OPEN (2, STATUS=' OLD' , FILE=NAME)

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PI=3. 141592653589793
II=0
A33=(1. 0D0, 0. 0D0)
PO=0. 3D0

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データの読み込み

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READ (2, *) PSI1, PSI2, G1, G2, G3, C1, C2
READ (2, *) PSI1, G1, G2
PSI1=-PSI1
PSI2=PSI1+180. D0
G3=G1
C1=1000
C2=C1

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DO 100 I=1, 1000
READ (2, *, END=110) FAII (I), RRE (I), RIM (I)
II=I

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*   WRITE (6, *) FAII (I)
100 CONTINUE
110 CLOSE (2)

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出力用ファイルオープン

OPEN (3, STATUS=' UNKNOWN' , FILE=NA)

DO 120 J=1, II

KFAI=FAII (J)

IF (KFAI. EQ. KAKU) THEN

IF (FAII (J). EQ. 180. 5) FAII (J)=180. 0

IF (FAII (J). EQ. 359. 5) FAII (J)=360. 0

ページ (1)

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                                SM12I. FOR
WRITE (3, *) PSI1, PSI2, G1, G2, G3, C1, C2, FAI (J), RRE (J), RIM (J)
FAI=FAI (J)
RRL=RRE (J)
RIL=RIM (J)
CALL FD1 (FAI, RRL, RIL, PSI1, PSI2, G1, G2, G3, C1, C2, PO, A33)
ENDIF
120 CONTINUE
C
CLOSE (3)
C
OPEN (2, STATUS=' OLD', FILE=' GO. DAT' )
OPEN (3, STATUS=' UNKNOWN', FILE=' URO. DAT' )
OPEN (4, STATUS=' UNKNOWN', FILE=' USO. DAT' )
OPEN (7, STATUS=' UNKNOWN', FILE=' SRO. DAT' )
OPEN (8, STATUS=' UNKNOWN', FILE=' SSO. DAT' )
OPEN (9, STATUS=' UNKNOWN', FILE=' TRSO. DAT' )
C
DO 208 J=1, 2
READ (2, *) PSI1, PSI2, G1, G2, G3, C1, C2, FAI, RE, RI
DO 108 I=0, KAKU
READ (2, *) SIT
READ (2, *) URR, URI, USR, USI
WRITE (3, 29) SIT, URR
WRITE (4, 29) SIT, USR
READ (2, *) SRR, SRI, SSR, SSI, TRSR, TRSI
WRITE (7, 29) SIT, SRR
WRITE (8, 29) SIT, SSR
WRITE (9, 29) SIT, TRSR
READ (2, *) Z1, Z2, Z3, Z4, Z5, Z6, Z7, Z8, Z9, Z10
108 CONTINUE
IF (J. EQ. 2) GO TO 208
WRITE (3, *) '      =      ='
WRITE (4, *) '      =      ='
WRITE (7, *) '      =      ='
WRITE (8, *) '      =      ='
WRITE (9, *) '      =      ='
208 CONTINUE
29 format (1H , 2E15. 8)
C
STOP
END
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1 1 行 1 2 列の行列
SUBROUTINE FD1 (FAI, RR, RI, PSI1, PSI2, G1, G2, G3, C1, C2, PO, A33)
IMPLICIT DOUBLE PRECISION (A-H, O-Z)
INTEGER ERR, L, K, N
REAL*8 FAI, FA, RR, RI, G1, G2, G3, AR (11, 12), AI (11, 12), EPS, PI
1 , PSI1, PSI2, C1, C2, PO, QK, T1, T2
COMPLEX*16 RAM, A (11, 12),
1 RP, RM, RK, RL, P, Q, R, A1, A2, A4, B1, B2, B4, SA1, SA2, SA4, SB1, SB2, SB4,
2 CA1, CA2, CA4, CB1, CB2, CB4, BB1, BB2, BB3, A11, A12, A13, A14, A21, A22,
3 A23, A24, A31, A32, A33, A34
DATA L, K, N, EPS/11, 11, 12, 1. E-12/

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RAM=DCMPLX(RR, RI)
PI=3.1415926D0
QK=3.0D0-4.0D0*PO
RP=RAM+1.0D0
RM=RAM-1.0D0
RK=RAM-QK
RL=RAM+QK
P=RP/RK
Q=RM/RK
R=RL/RK
FA=FAI*PI/180.0D0
T1=(FAI/2.0D0+PSI1)*PI/180.0D0
T2=(FAI/2.0D0+PSI2)*PI/180.0D0
A1=RP*T1
A2=RP*T2
A4=RP*FA
B1=RM*T1
B2=RM*T2
B4=RM*FA
SA1=CDSIN(A1)
SA2=CDSIN(A2)
SA4=CDSIN(A4)
SB1=CDSIN(B1)
SB2=CDSIN(B2)
SB4=CDSIN(B4)
CA1=CD COS(A1)
CA2=CD COS(A2)
CA4=CD COS(A4)
CB1=CD COS(B1)
CB2=CD COS(B2)
CB4=CD COS(B4)
BB1=CA4/(Q*SB4)
BB2=-SA4/(Q*SB4)
BB3=CB4/SB4

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DO 30 L1=1, K
  DO 40 L2=1, N
    A(L1, L2)=(0.0D0, 0.0D0)
40 CONTINUE
30 CONTINUE

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A(1, 2)=1.0D0
A(1, 4)=P
A(2, 1)=1.0D0
A(2, 3)=Q
A(3, 1)=G1 *SA1
A(3, 2)=G1 *CA1
A(3, 3)=G1*P*SB1
A(3, 4)=G1*P*CB1
A(3, 5)=-G2 *SA1
A(3, 6)=-G2 *CA1
A(3, 7)=-G2*P*SB1
A(3, 8)=-G2*P*CB1
A(4, 1)= CA1
A(4, 2)= -SA1
A(4, 3)= R*CB1

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A(4, 4)=-R*SB1
A(4, 5)= -CA1
A(4, 6)= SA1
A(4, 7)=-R*CB1
A(4, 8)= R*SB1
A(5, 1)= 2. ODO*G1 *CA1-C1*SA1
A(5, 2)=-2. ODO*G1 *SA1-C1*CA1
A(5, 3)= 2. ODO*G1*Q*CB1-C1*SB1
A(5, 4)=-2. ODO*G1*Q*SB1-C1*CB1
A(5, 5)=C1*SA1
A(5, 6)=C1*CA1
A(5, 7)=C1*SB1
A(5, 8)=C1*CB1
A(6, 1)=-C1*SA1
A(6, 2)=-C1*CA1
A(6, 3)=-C1*SB1
A(6, 4)=-C1*CB1
A(6, 5)= 2. ODO*G2 *CA1+C1*SA1
A(6, 6)=-2. ODO*G2 *SA1+C1*CA1
A(6, 7)= 2. ODO*G2*Q*CB1+C1*SB1
A(6, 8)=-2. ODO*G2*Q*SB1+C1*CB1
A(7, 5)=-G2 *SA2
A(7, 6)=-G2 *CA2
A(7, 7)=-G2*P*SB2
A(7, 8)=-G2*P*CB2
A(7, 9)= G3*(SA2+BB1*P*CB2)
A(7, 10)= G3*(CA2+BB2*P*CB2)
A(7, 12)=-G3*P*(SB2+BB3*CB2)*A33
A(8, 5)= CA2
A(8, 6)= -SA2
A(8, 7)= R*CB2
A(8, 8)=-R*SB2
A(8, 9)= -CA2+BB1*R*SB2
A(8, 10)= SA2+BB2*R*SB2
A(8, 12)= R*(CB2-BB3*SB2)*A33
A(9, 5)= 2. ODO*G2 *CA2-C2*SA2
A(9, 6)=-2. ODO*G2 *SA2-C2*CA2
A(9, 7)= 2. ODO*G2*Q*CB2-C2*SB2
A(9, 8)=-2. ODO*G2*Q*SB2-C2*CB2
A(9, 9)=C2*(SA2+BB1*CB2)
A(9, 10)=C2*(CA2+BB2*CB2)
A(9, 12)=-C2*(SB2+BB3*CB2)*A33
A(10, 5)=-C2*SA2
A(10, 6)=-C2*CA2
A(10, 7)=-C2*SB2
A(10, 8)=-C2*CB2
A(10, 9)= 2. DO*G3*CA2+C2*SA2-2. DO*BB1*G3*Q*SB2+BB1*C2*CB2
A(10, 10)=-2. DO*G3*SA2+C2*CA2-2. DO*BB2*G3*Q*SB2+BB2*C2*CB2
A(10, 12)=-2. DO*G3*Q*CB2+C2*SB2-2. DO*BB3*G3*Q*SB2+BB3*C2*CB2)*A33
A(11, 9)=BB1
A(11, 10)=BB2
A(11, 11)=-1. ODO
A(11, 12)=-BB3*A33

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DO 10 I=1, K
DO 20 J=1, N

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        AR(I, J) = REAL(A(I, J))
        AI(I, J) = AIMAG(A(I, J))
20 CONTINUE
10 CONTINUE
CALL CGAUJ(AR, AI, L, K, N, EPS, ERR)
C      WRITE(6, *) ' ERR=' , ERR
C      WRITE(6, *) ' RAM=' , RAM
        A11=DCMPLX(AR(1, N), AI(1, N))
        A12=DCMPLX(AR(2, N), AI(2, N))
        A13=DCMPLX(AR(3, N), AI(3, N))
        A14=DCMPLX(AR(4, N), AI(4, N))
        A21=DCMPLX(AR(5, N), AI(5, N))
        A22=DCMPLX(AR(6, N), AI(6, N))
        A23=DCMPLX(AR(7, N), AI(7, N))
        A24=DCMPLX(AR(8, N), AI(8, N))
        A31=DCMPLX(AR(9, N), AI(9, N))
        A32=DCMPLX(AR(10, N), AI(10, N))
        A33=(1.0D0, 0.0D0)
        A34=DCMPLX(AR(11, N), AI(11, N))
1      CALL F12(G1, G2, G3, PO, RAM, A11, A12, A13, A14,
        A21, A22, A23, A24, A31, A32, A33, A34, FAI, PSI1, PSI2)
RETURN
END

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## 1 2元の場合の応力と変位

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SUBROUTINE F12(G1, G2, G3, PO, RAM, A11, A12, A13, A14,
1 A21, A22, A23, A24, A31, A32, A33, A34, FAI, PSI1, PSI2)
REAL*8 G1, G2, G3, FAI, PSI1, PSI2, SIT, HAN1, HAN2, PO, QK
COMPLEX*16 RAM, A11, A12, A13, A14, A21, A22, A23, A24, A31, A32, A33, A34,
1 UR, US, SR, SS, TRS, UX, UY, SX, SY, TXY
QK=3.0D0-4.0D0*PO
HAN1=FAI/2.0D0+PSI1
HAN2=FAI/2.0D0+PSI2
IBEG=0
IEND=INT(FAI)
DO 10 I=IBEG, IEND
    SIT=FLOAT(I)
    IF (SIT.GE.0.0.AND.SIT.LE.HAN1) THEN
        CALL UST(RAM, A11, A12, A13, A14, G1, QK, SIT, UR, US, SR, SS, TRS)
    ENDIF
    IF (SIT.GT.HAN1.AND.SIT.LT.HAN2) THEN
        CALL UST(RAM, A21, A22, A23, A24, G2, QK, SIT, UR, US, SR, SS, TRS)
    ENDIF
    IF (SIT.GE.HAN2.AND.SIT.LE.FAI) THEN
        CALL UST(RAM, A31, A32, A33, A34, G3, QK, SIT, UR, US, SR, SS, TRS)
    ENDIF
    WRITE(3, 600) SIT
    WRITE(3, 601) UR, US
    WRITE(3, 602) SR, SS, TRS
    CALL HXY(SIT, UR, US, UX, UY)
    CALL OXY(SIT, SR, SS, TRS, SX, SY, TXY)
    WRITE(3, 601) UX, UY
    WRITE(3, 602) SX, SY, TXY
10 CONTINUE
600 FORMAT(F8.3)

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## SM12I. FOR

601 FORMAT (4E15. 7)

602 FORMAT (6E15. 7)

RETURN

END

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応力及び変位の公式（すべり問題における）

SUBROUTINE UST (R, A1, A2, A3, A4, G, QK, SI, UR, US, SR, SS, TRS)

IMPLICIT DOUBLE PRECISION (A-H, O-Z)

REAL\*8 G, QK, S, SI, PI

COMPLEX\*16 R, R1, R2, A1, A2, A3, A4, UR, US, SR, SS, TRS, B, F11, F12, F13,

1 F14, F21, F22, F23, F24, C, F31, F32, F33, F34, D, F41, F42,

2 F43, F44, E, F51, F52, F53, F54, RK

PI =3. 1415926D0

S =SI\*PI/180. 0D0

R1 =R+1. 0D0

R2 =R-1. 0D0

RK =R-QK

B =(R+QK)/RK

C =2. 0\*R\*(R-3. 0D0)/RK

D =2. 0\*R\*R1/RK

E =2. 0\*R\*R2/RK

F11=A1\*CDSIN (R1\*S)

F12=A2\*CDCOS (R1\*S)

F13=A3\*CDSIN (R2\*S)

F14=A4\*CDCOS (R2\*S)

F21=A1\*CDCOS (R1\*S)

F22=A2\*CDSIN (R1\*S)

F23=B\*A3\*CDCOS (R2\*S)

F24=B\*A4\*CDSIN (R2\*S)

F31=2. 0\*R\*F11

F32=2. 0\*R\*F12

F33=C\*F13

F34=C\*F14

F41=-2. 0\*R\*F11

F42=-2. 0\*R\*F12

F43=-D\*F13

F44=-D\*F14

F51=2. 0\*R\*F21

F52=2. 0\*R\*(-F22)

F53=E\*A3\*CDCOS (R2\*S)

F54=E\*(-A4)\*CDSIN (R2\*S)

UR =F11+F12+F13+F14

US =F21-F22+F23-F24

SR =G\*(F31+F32+F33+F34)

SS =G\*(F41+F42+F43+F44)

TRS=G\*(F51+F52+F53+F54)

RETURN

END

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サブルーチン CGAUJ

複素係数連立 1 次方程式の根を得る

SUBROUTINE CGAUJ (AR, AI, L, M, N, EPS, ERR)

IMPLICIT DOUBLE PRECISION (A-H, O-Z)

INTEGER WORK (500), I, IW, J, K, K1, L, LC, LR, M, M1, M2, N, ERR

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                                SM12I. FOR
REAL*8 AR(L, N), AI(L, M), EPS, WMAX, W, PIVOT, WR, WI, W1, W2
IF (M. LT. 2. 0. OR. M. GT. 500. OR. M. GE. N. OR. EPS. LE. 0. 0) THEN
  ERR=999
ELSE
  DO 10 I=1, M
    WORK(I)=I
10  CONTINUE
    DO 110 K=1, M
      WMAX=0. 000
      DO 30 I=K, M
        DO 20 J=K, M
          W=AR(I, J)**2+AI(I, J)**2
          IF (W. GT. WMAX) THEN
            WMAX=W
            LC=J
            LR=I
          ENDIF
20  CONTINUE
30  CONTINUE
      PIVOT=AR(LR, LC)**2+AI(LR, LC)**2
      IF (PIVOT. LE. EPS) THEN
        ERR=1
        RETURN
      ENDIF
      IF (K. NE. LC) THEN
        IW=WORK(K)
        WORK(K)=WORK(LC)
        WORK(LC)=IW
        DO 40 I=1, M
          WR=AR(I, K)
          WI=AI(I, K)
          AR(I, K)=AR(I, LC)
          AI(I, K)=AI(I, LC)
          AR(I, LC)=WR
          AI(I, LC)=WI
40  CONTINUE
        ENDIF
        IF (K. NE. LR) THEN
          DO 60 J=K, N
            WR=AR(LR, J)
            WI=AI(LR, J)
            AR(LR, J)=AR(K, J)
            AI(LR, J)=AI(K, J)
            AR(K, J)=WR
            AI(K, J)=WI
60  CONTINUE
          ENDIF
          WR= AR(K, K)/PIVOT
          WI=-AI(K, K)/PIVOT
          K1=K+1
          DO 80 I=K1, N
            W=AR(K, I)*WR-AI(K, I)*WI
            AI(K, I)=AR(K, I)*WI+AI(K, I)*WR
            AR(K, I)=W
80  CONTINUE
          DO 100 I=1, M

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      IF (I.NE.K) THEN
        WR=AR(I,K)
        WI=AI(I,K)
        DO 90 J=K1,N
          W1=AR(K,J)*WR-AI(K,J)*WI
          W2=AR(K,J)*WI+AI(K,J)*WR
          W=AR(I,J)-W1
          AI(I,J)=AI(I,J)-W2
          AR(I,J)=W
90      CONTINUE
        ENDIF
100     CONTINUE
110     CONTINUE
        M1=M-1
        DO 140 I=1,M1
120      K=WORK(I)
        IF (K.NE.I) THEN
          IW=WORK(K)
          WORK(K)=WORK(I)
          WORK(I)=IW
          M2=M+1
          DO 130 J=M2,N
            WR=AR(K,J)
            WI=AI(K,J)
            AR(K,J)=AR(I,J)
            AI(K,J)=AI(I,J)
            AR(I,J)=WR
            AI(I,J)=WI
130          CONTINUE
          GOTO 120
        ENDIF
140     CONTINUE
        ERR=0
      ENDIF
      RETURN
      END

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応力  $\sigma_x, \sigma_y, \tau_{xy}$  を求める

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SUBROUTINE OXY(SIT, SR, SS, TRS, SX, SY, TXY)
  IMPLICIT DOUBLE PRECISION (A-H, O-Z)
  REAL*8 SIT, PI, S
  COMPLEX*16 SR, SS, TRS, SX, SY, TXY
  PI =3.1415926D0
  S =SIT*PI/180.D0
  SN =DSIN(S)
  CS =DCOS(S)
  SX =SR*CS**2+SS*SN**2-2.D0*CS*SN*TRS
  SY =SR*SN**2+SS*CS**2+2.D0*CS*SN*TRS
  TXY=(SR-SS)*CS*SN+(CN**2-SN**2)*TRS
  RETURN
  END

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変位  $U_x, U_y$  を求める

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SUBROUTINE HXY(SIT, UR, US, UX, UY)

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SM12I.FOR
IMPLICIT DOUBLE PRECISION (A-H, O-Z)
REAL*8 SIT, PI, S
COMPLEX*16 UR, US, UX, UY
PI =3.1415926D0
S =SIT*PI/180.0D0
SN =DSIN(S)
CS =DCOS(S)
UX =UR*CS-US*SN
UY =UR*SN+US*CS
RETURN
END
```